

A Systematic Approach to MDD-Based Constraint Programming

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- Domain store communicates **limited information** between constraints.
 - Other structural information learned by a constraint is lost.
 - It must be projected onto variable domains
- Domain store provides a **very coarse relaxation** of solution space.
 - Cartesian product of variable domains.
- **Imbalance** of search and inference.
 - Node processing to infer structure doesn't pay off.
 - Must process many nodes quickly.

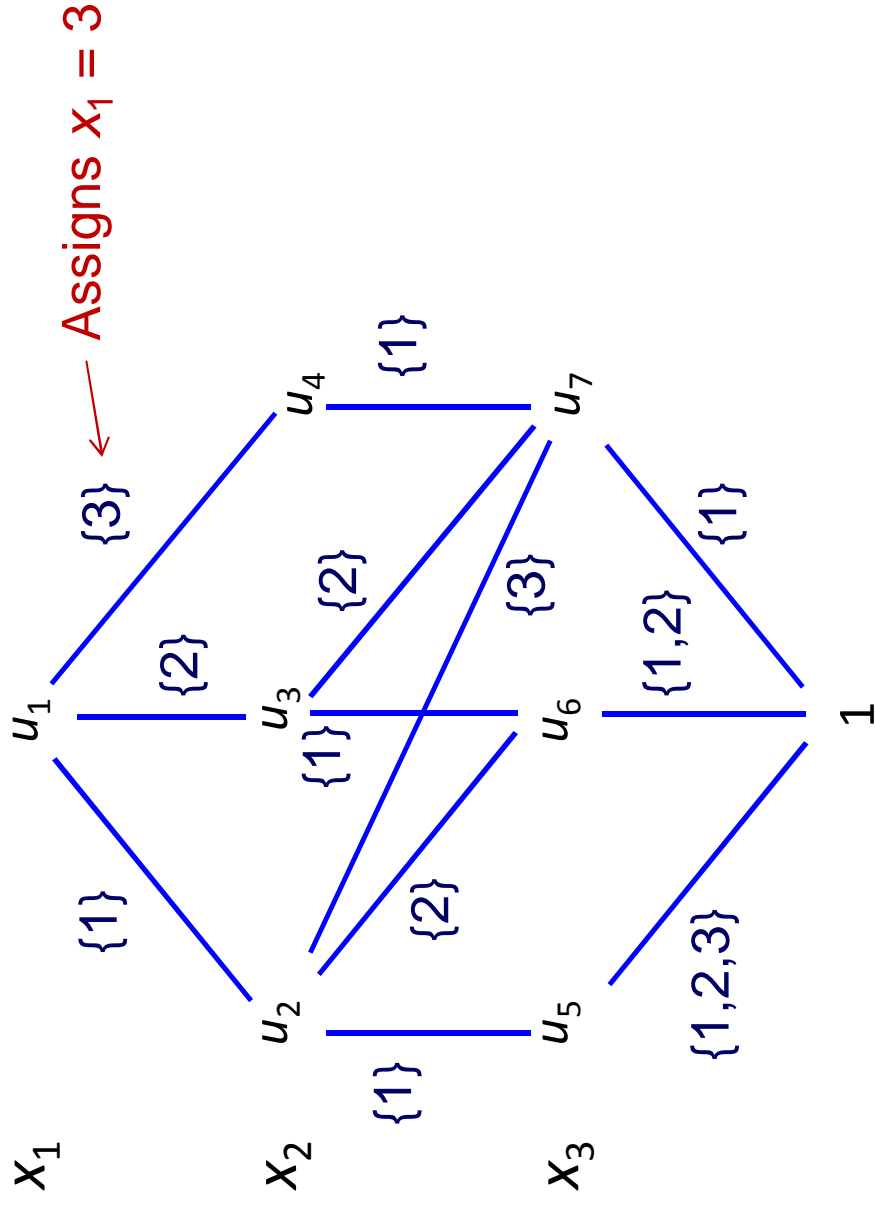
- Replace domain store with a limited-width **multivalued decision diagram (MDD)**.
 - Andersen, Hadzic, Hooker, Tiedemann (2007)
 - Domain store is a special case (width = 1).
- Propagate constraints through the MDD.
 - Use **node splitting** (refinement) and **edge domain filtering**.
- MDD provides a more refined relaxation.
 - Recognizes some variable interactions.
- Easily adapted to optimization.
 - Shortest path computation

- Show that MDD-based propagation can follow a standard pattern.
 - And yet can be **specialized** to each type of constraint to exploit structure.
 - Implement a general **MDD-based constraint solver** based on this pattern.
- Test the MDD-based solver on a class of constraints.
 - Multiple **among** constraints.

MDD representing

$$x_1 + x_2 + x_3 \leq 5$$

$$x_j \in \{1, 2, 3\}$$

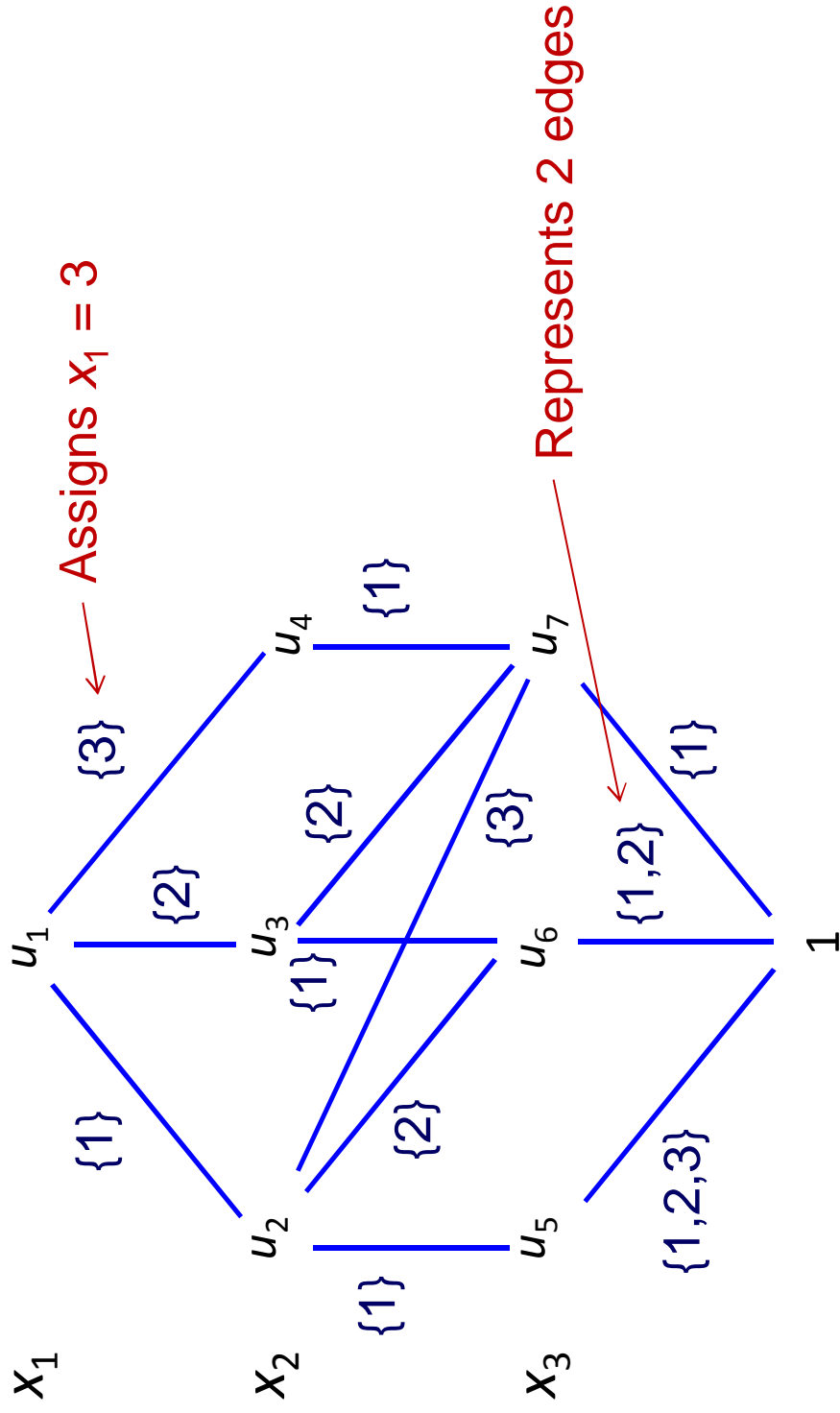


MDD basics

MDD representing

$$x_1 + x_2 + x_3 \leq 5$$

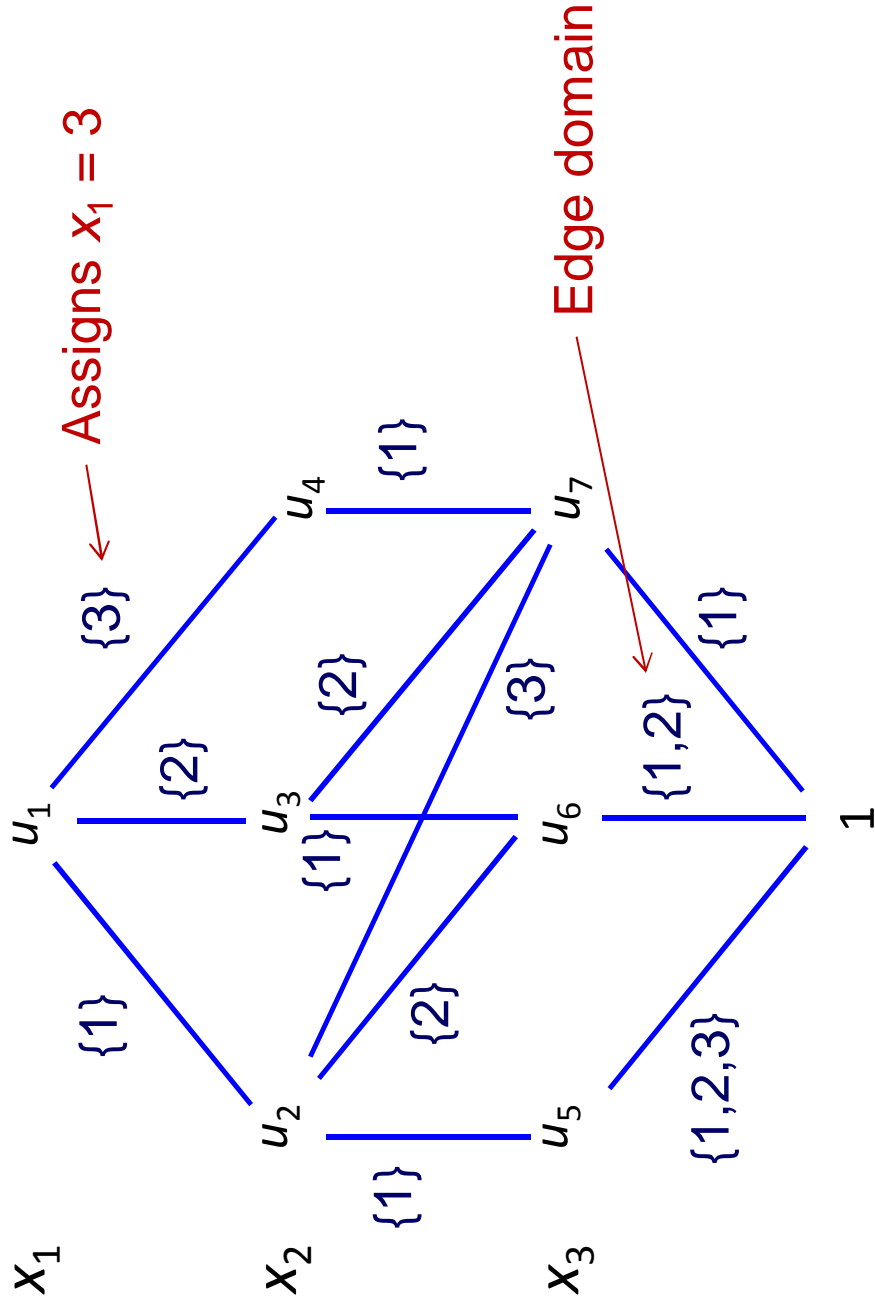
$$x_j \in \{1, 2, 3\}$$



MDD representing

$$x_1 + x_2 + x_3 \leq 5$$

$$x_j \in \{1, 2, 3\}$$

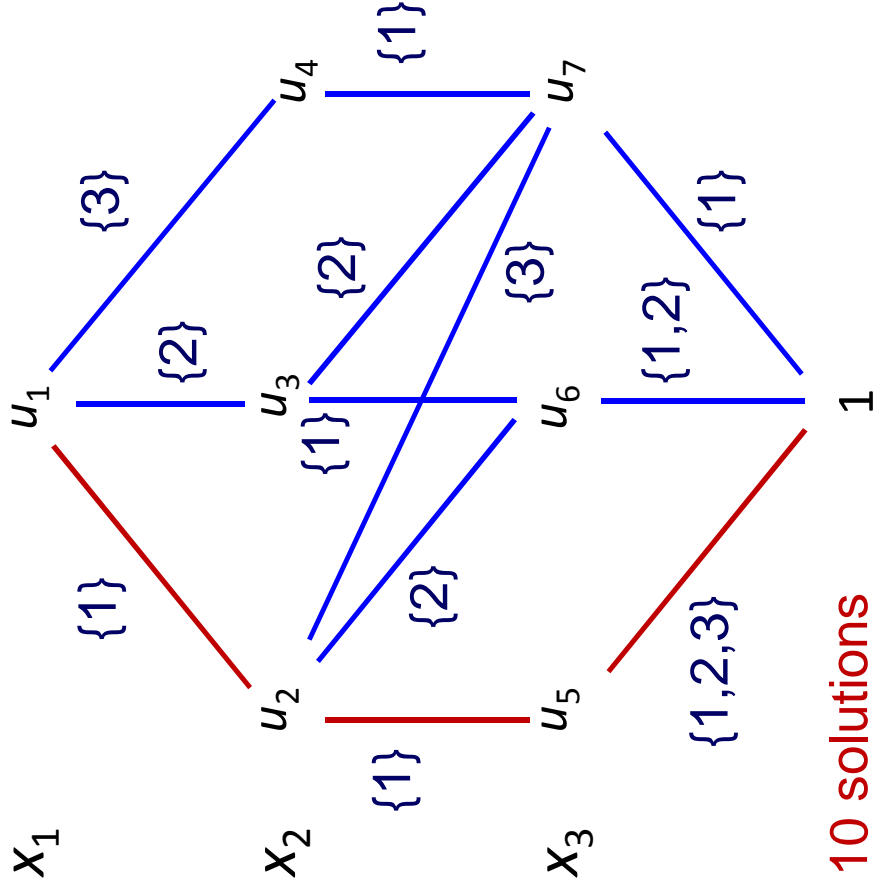


MDD basics

MDD representing

$$x_1 + x_2 + x_3 \leq 5$$

$$x_j \in \{1, 2, 3\}$$



Each path from top to bottom represents a set of solutions

$$\{1\} \times \{1\} \times \{1, 2, 3\} =$$

$$\{(1, 1, 1), (1, 1, 2), (1, 1, 3)\}$$

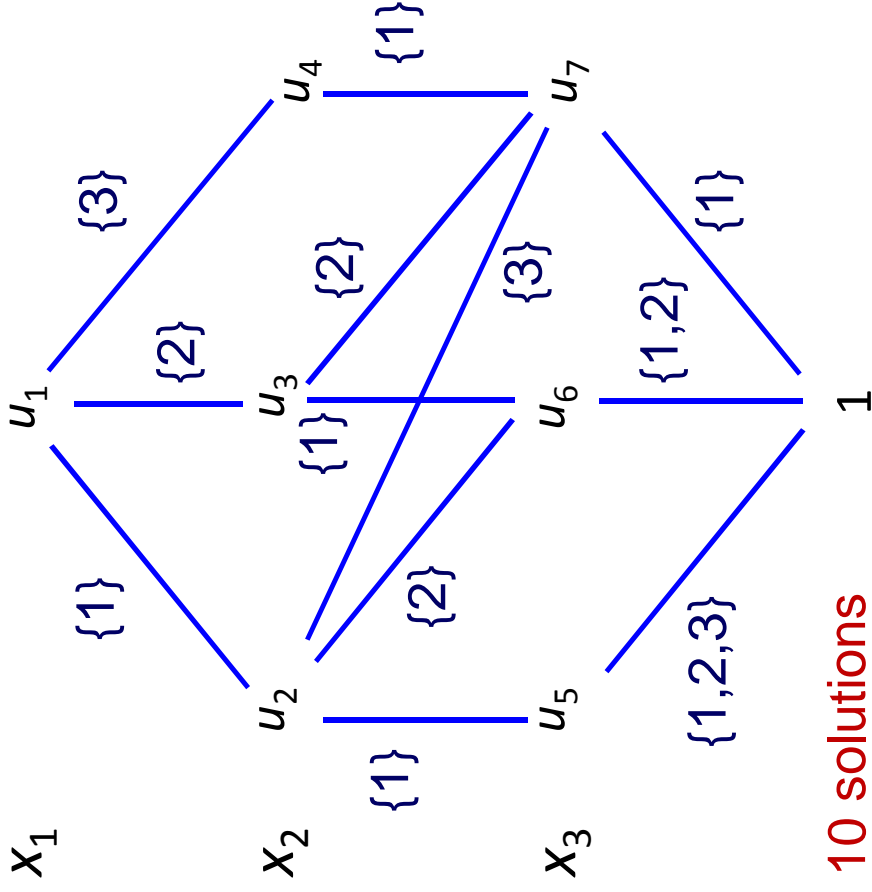
10 solutions total

MDD relaxation

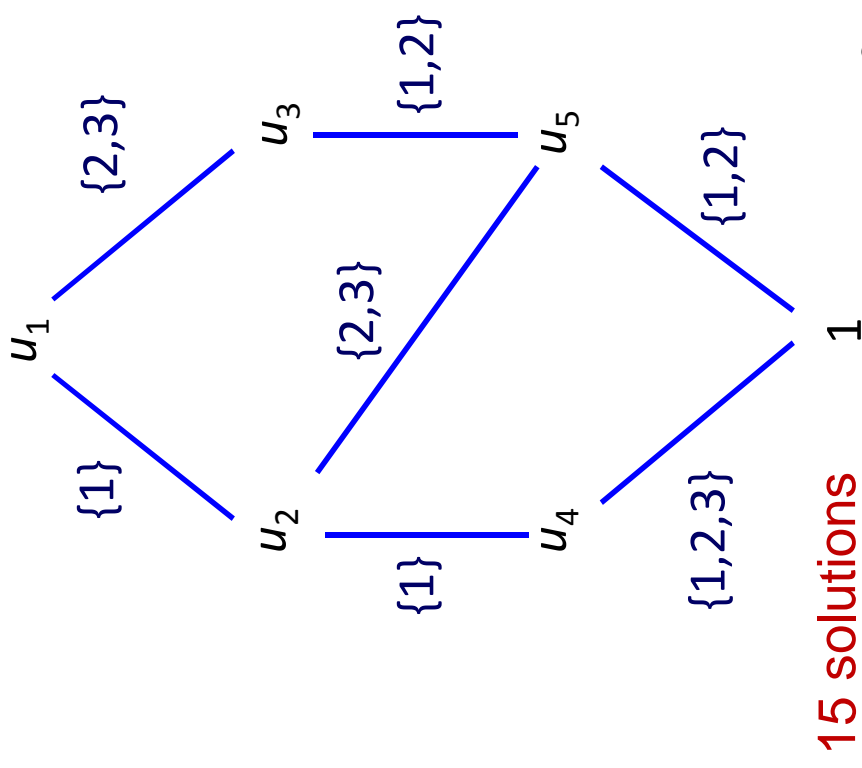
MDD representing

$$x_1 + x_2 + x_3 \leq 5$$

$$x_j \in \{1, 2, 3\}$$



A **relaxed** MDD (width 2) representing a superset of the solutions

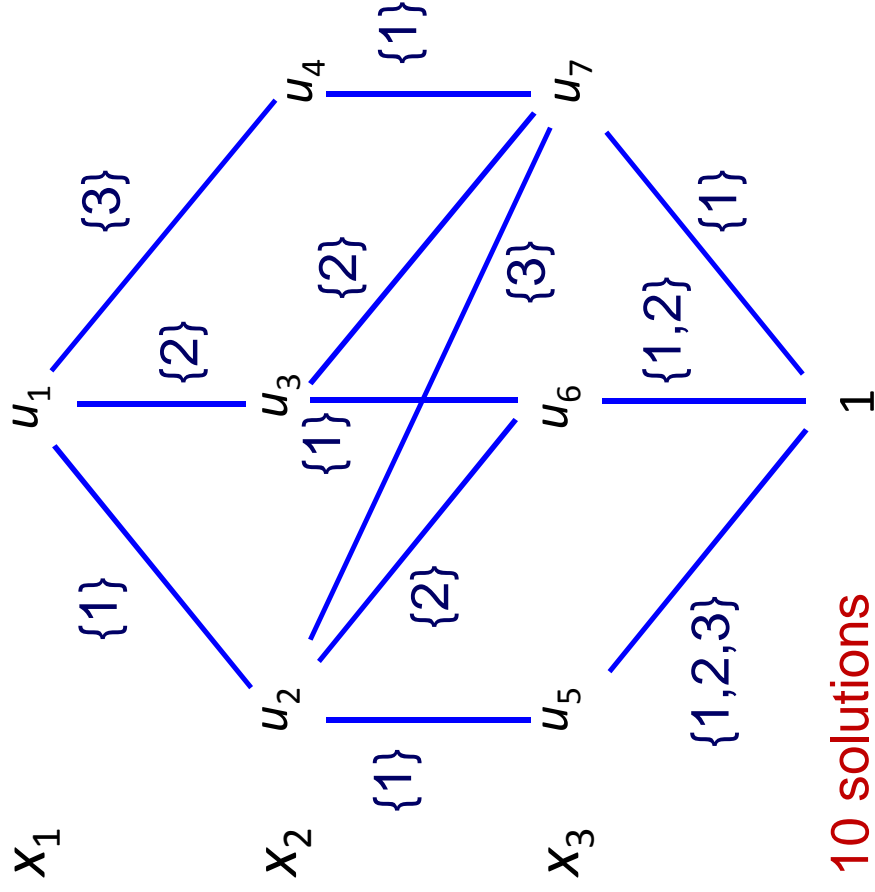


MDD relaxation

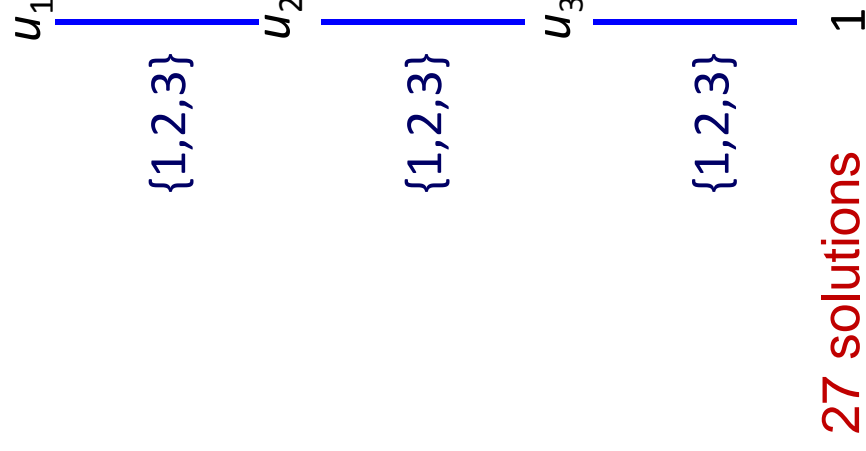
MDD representing

$$x_1 + x_2 + x_3 \leq 5$$

$$x_j \in \{1, 2, 3\}$$



Conventional domain store
(width 1 relaxation)



10 solutions

27 solutions

- We will use among constraint as a running example.
- At least L and at most U variables in set X take a value in set S :

 $\text{among}(X, S, L, U)$
- Applications in sequencing and scheduling, etc.

- Example: Employee scheduling

x_t = shift assigned on day t .

$S = \{M, A, N\} = \{\text{shifts}\}$

Between 2 and 4 afternoon/night shifts in a week:

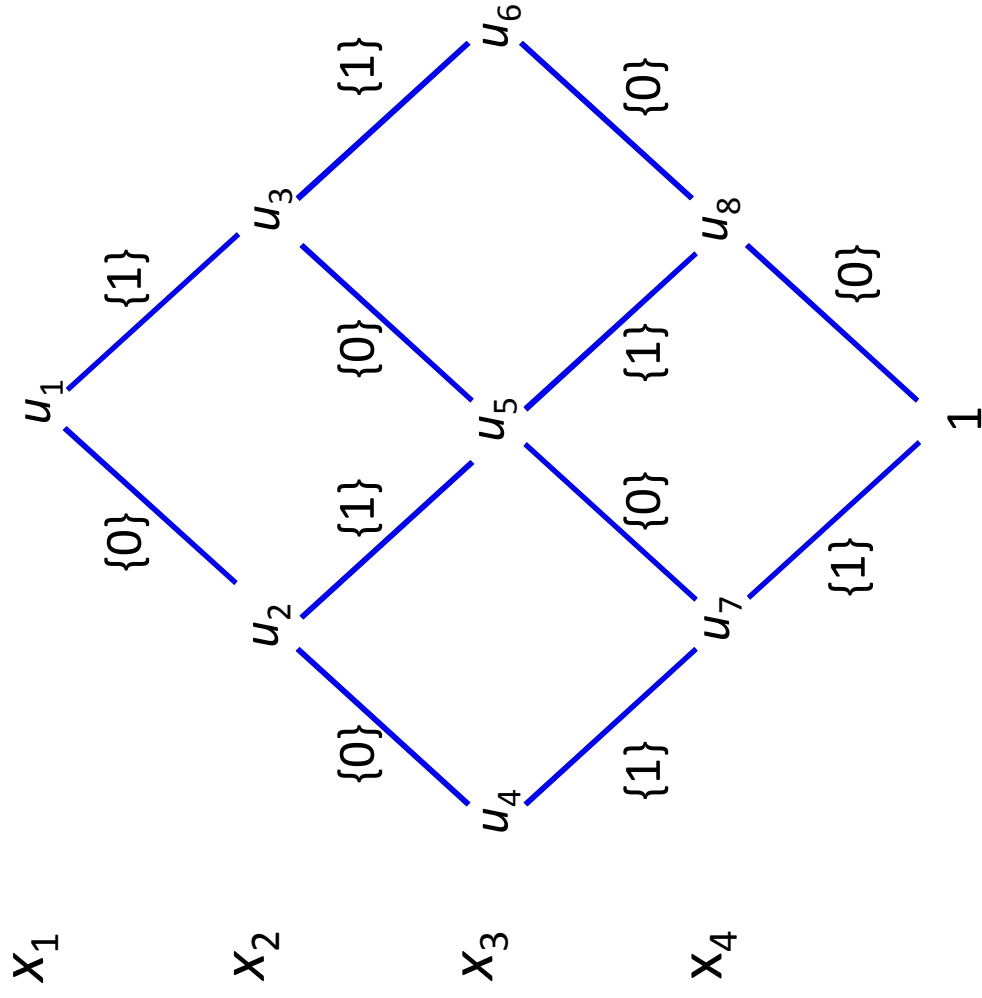
Among($\{x_1, \dots, x_7\}, \{A, N\}, 2, 4$)

t	1	2	3	4	5	6	7
x_t	M	A	N	M	M	A	M

WOLOG, suppose $x_t \in \{0,1\}$, $S = \{1\}$

t	1	2	3	4	5	6	7
x_t	0	1	1	0	0	1	0

Among constraint



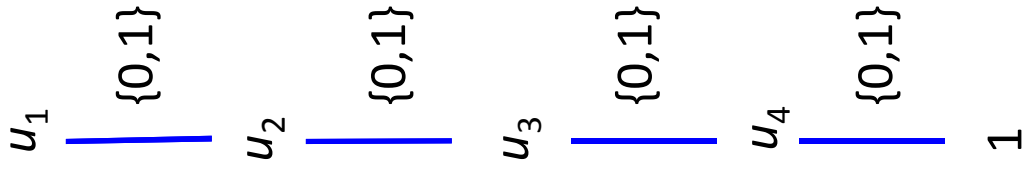
Exact MDD for among($\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$)

- Maintain limited-width MDD
 - Serves as relaxation
 - Typically start with width 1 (domain store)
 - Update MDD by propagating constraints sequentially
- Constraint Propagation
 - Edge filtering: Remove provably inconsistent edges
 - Node refinement: Split nodes to separate edge information
- Search
 - As in classical CP, but may now be guided by MDD
- Easily extended to optimization
 - Shortest path in MDD

Example

- We will propagate
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2)$
- through a BDD of maximum width 3
- All path lengths must be ≤ 2 .

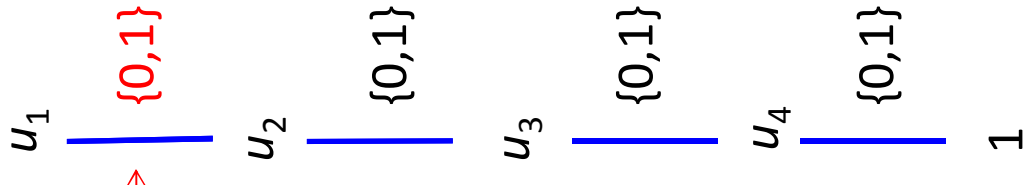
Example



Initially, the MDD has width 1
(traditional domain store)

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2)$

Example



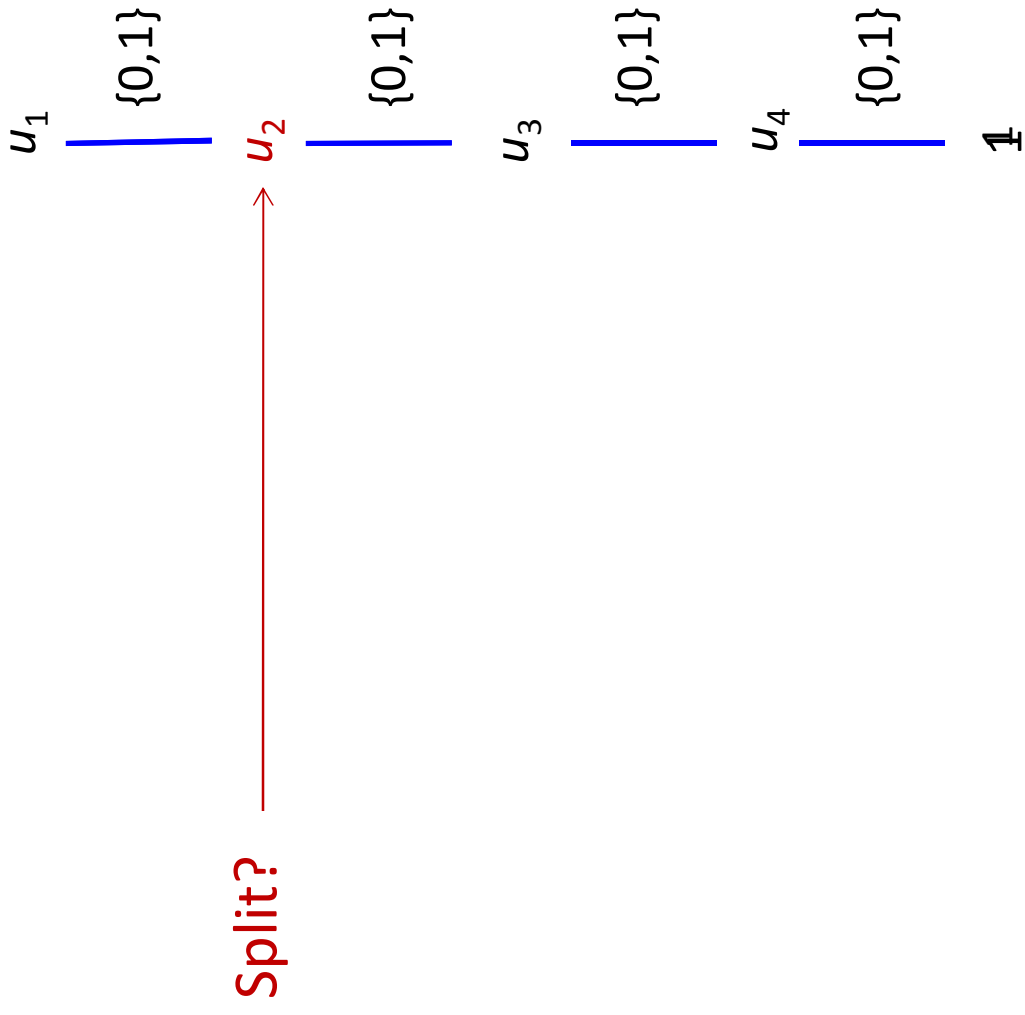
Try to filter edge domain $\{0,1\}$

No filtering possible.

Initially, the MDD has width 1
(traditional domain store)

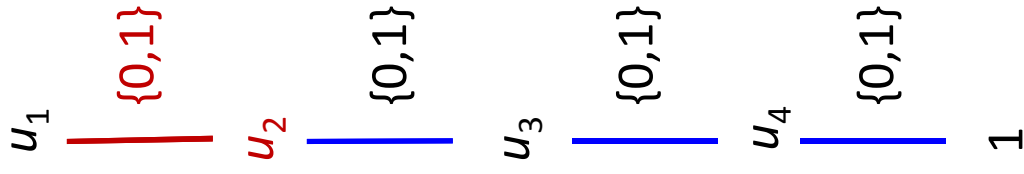
among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

Example



among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example



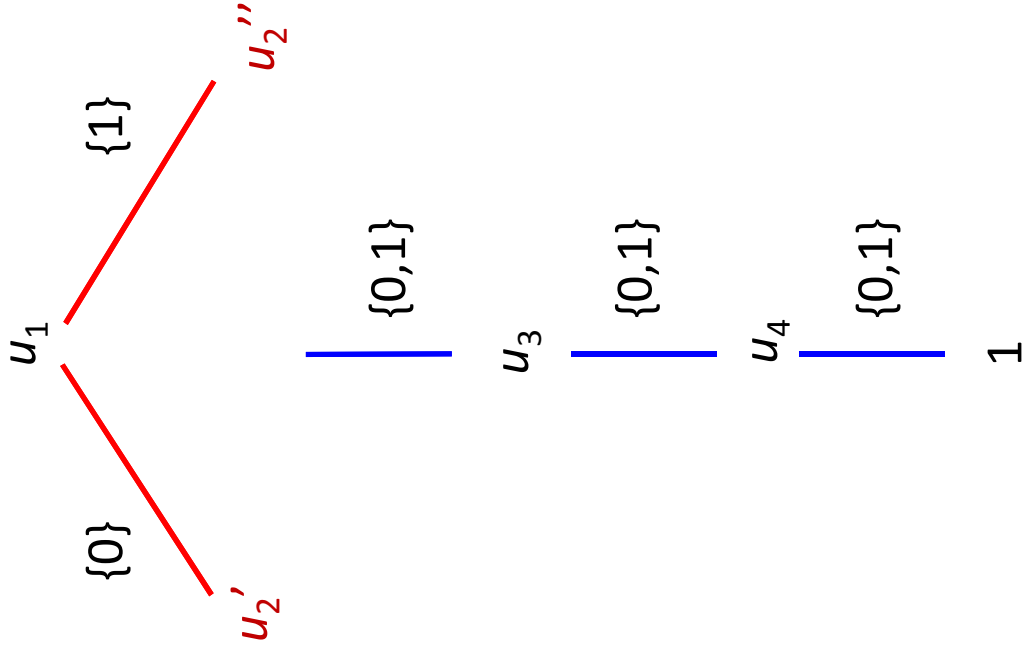
Split?

The 2 incoming edges
(length 0 and 1) are
not **equivalent**.

The partial assignments
 $x_1 = 0, x_1 = 1$
don't have the same set
of possible completions.

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2)$

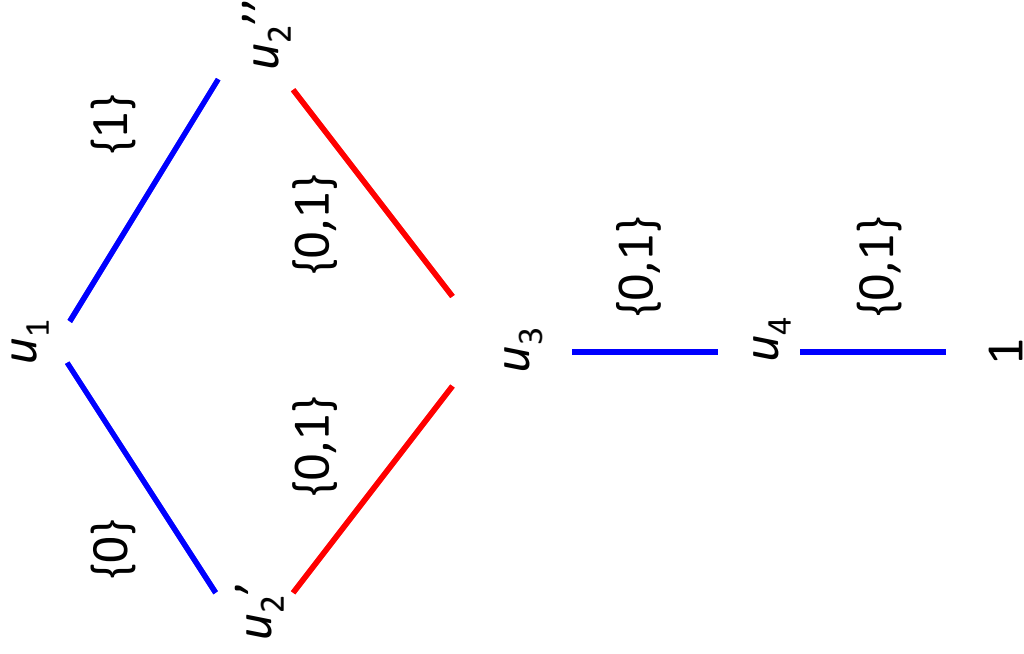
Example



So we split.
This doesn't exceed
max width of 3.

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2)$

Example

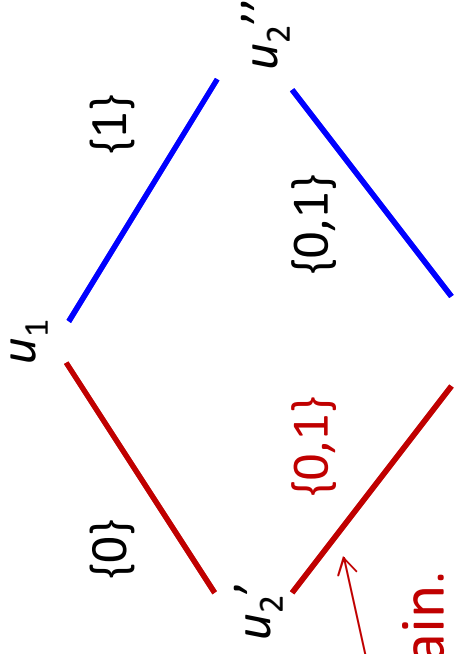


So we split.
This doesn't exceed
max width of 3.

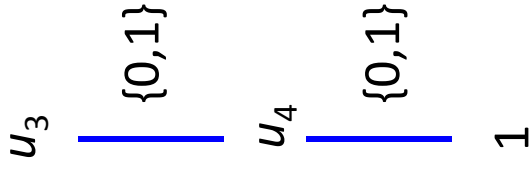
Duplicate outgoing
Edges.

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example

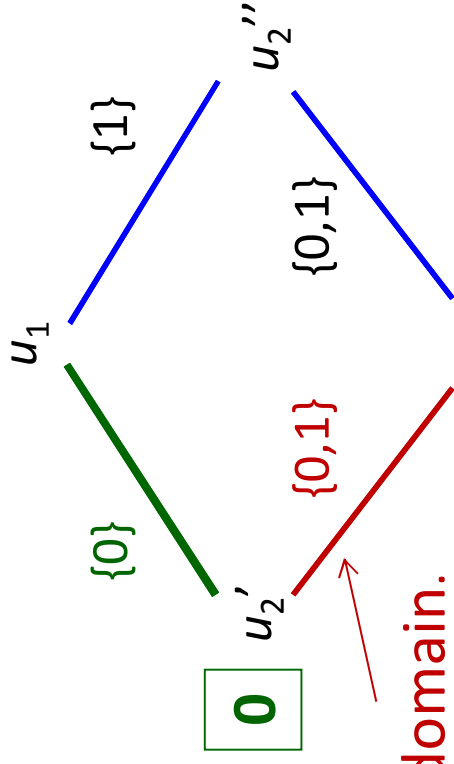


Try to filter edge domain.



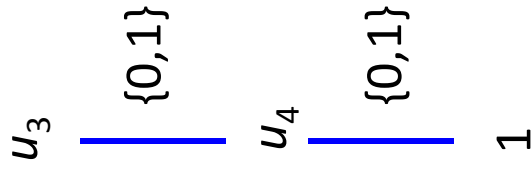
among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

Example



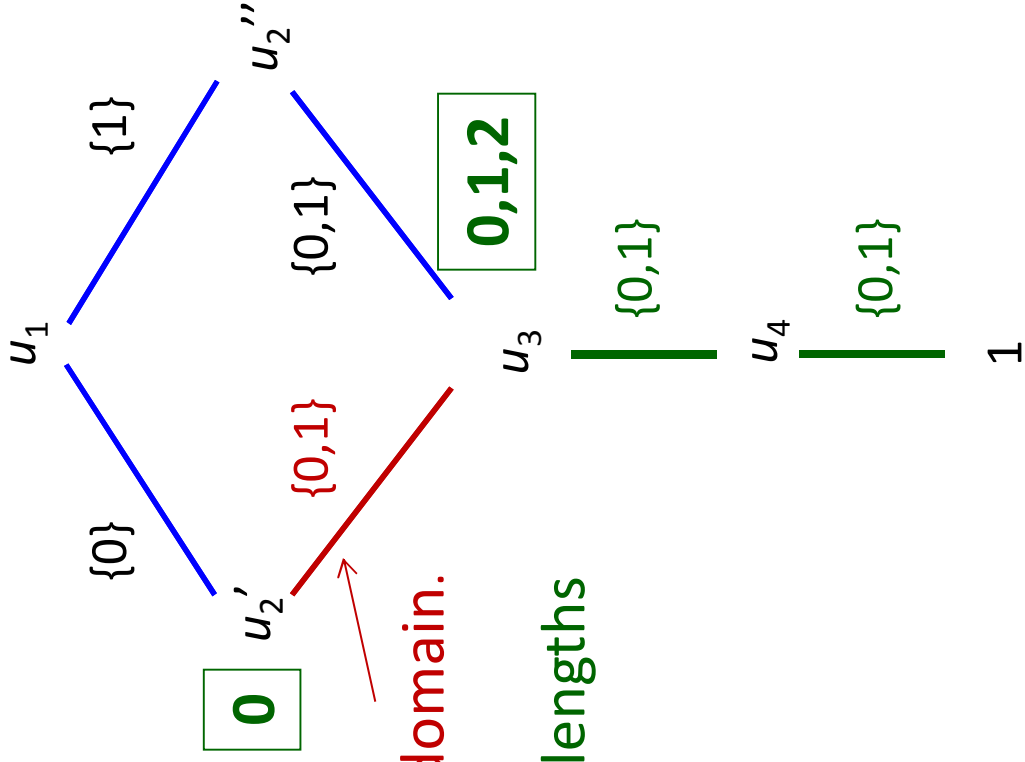
Try to filter edge domain.

Compute all path lengths
from top...



among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

Example

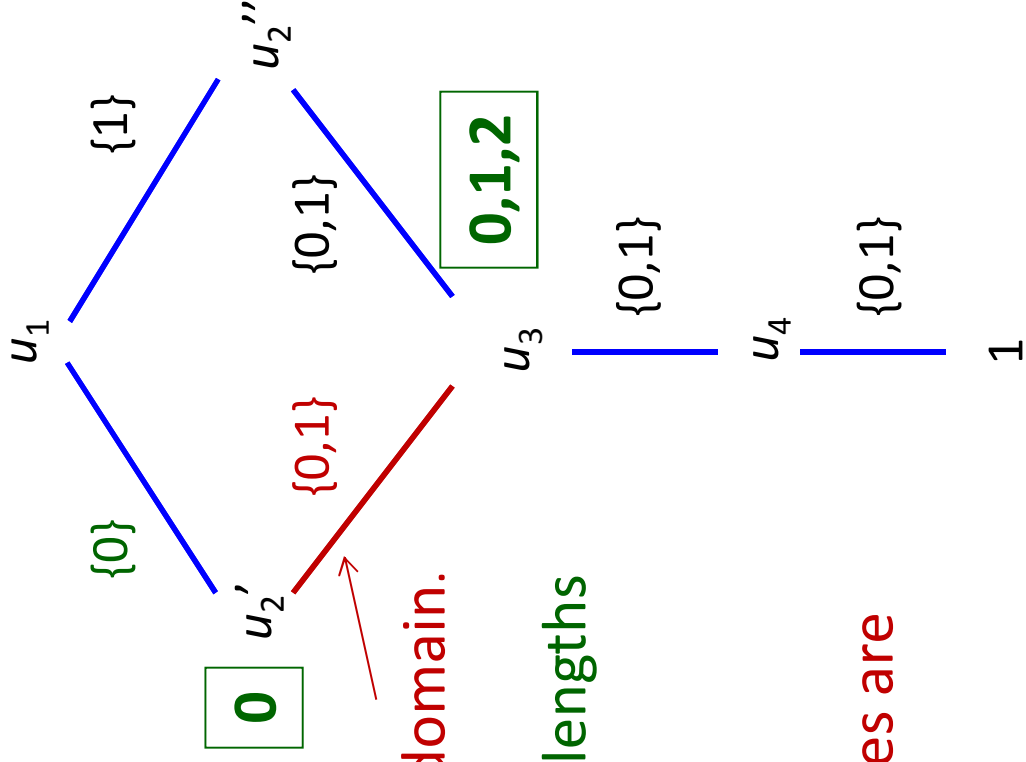


Try to filter edge domain.

Compute all path lengths
from top...
and from bottom.

among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

Example



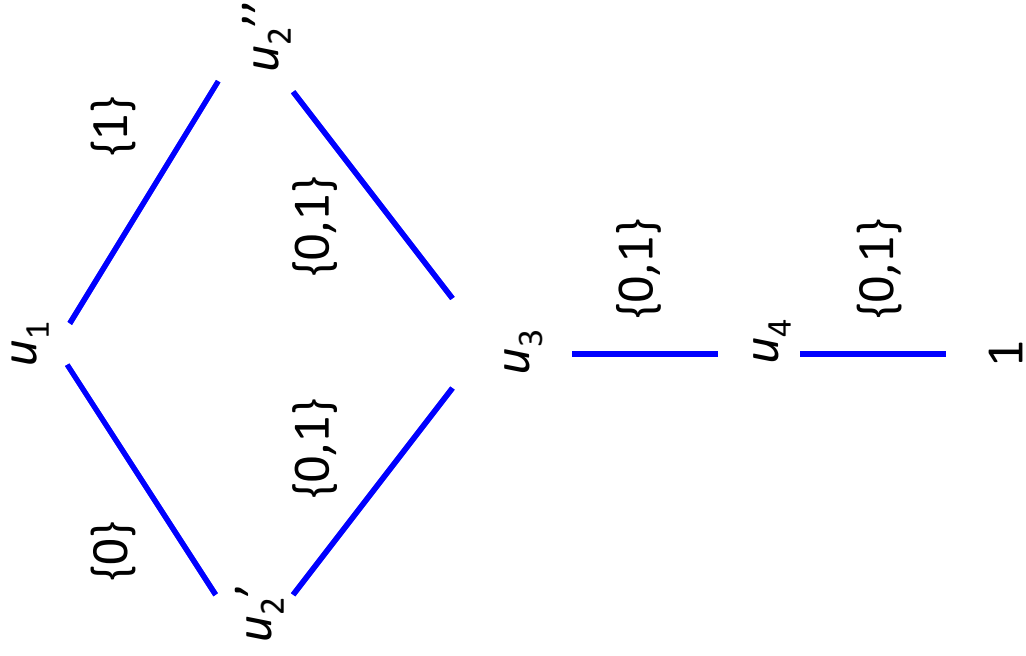
Try to filter edge domain.

Compute all path lengths
from top...
and from bottom.

Both domain values are
consistent.

among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

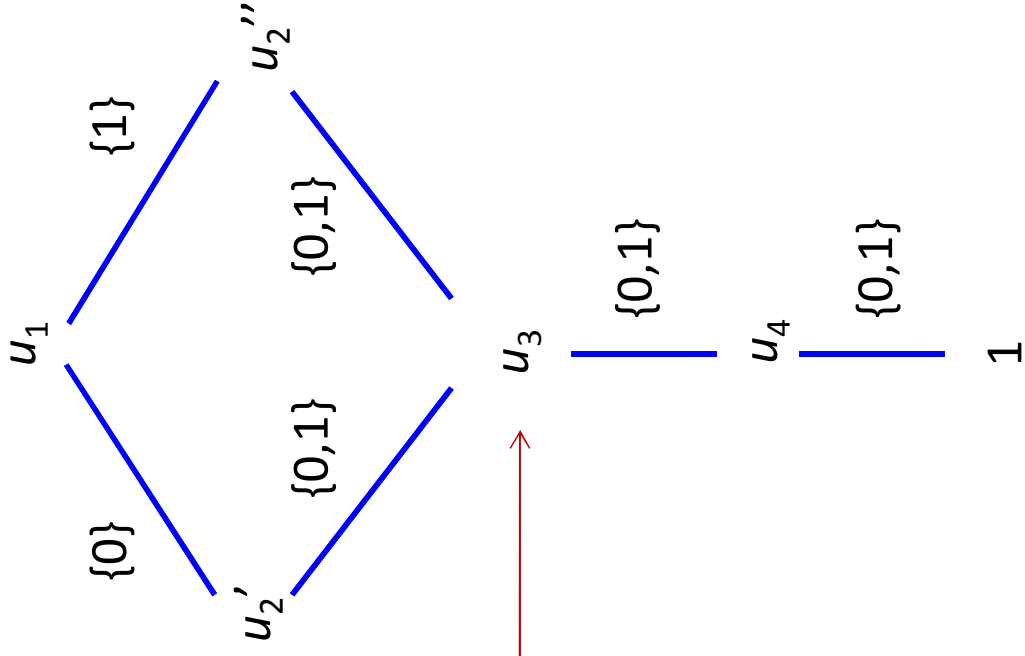
Example



No filtering possible for x_2 .

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

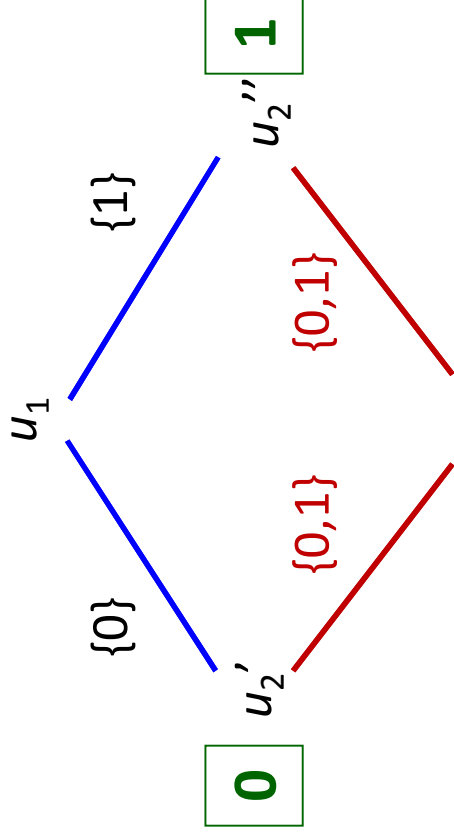
Example



Split?

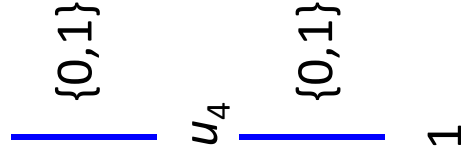
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example



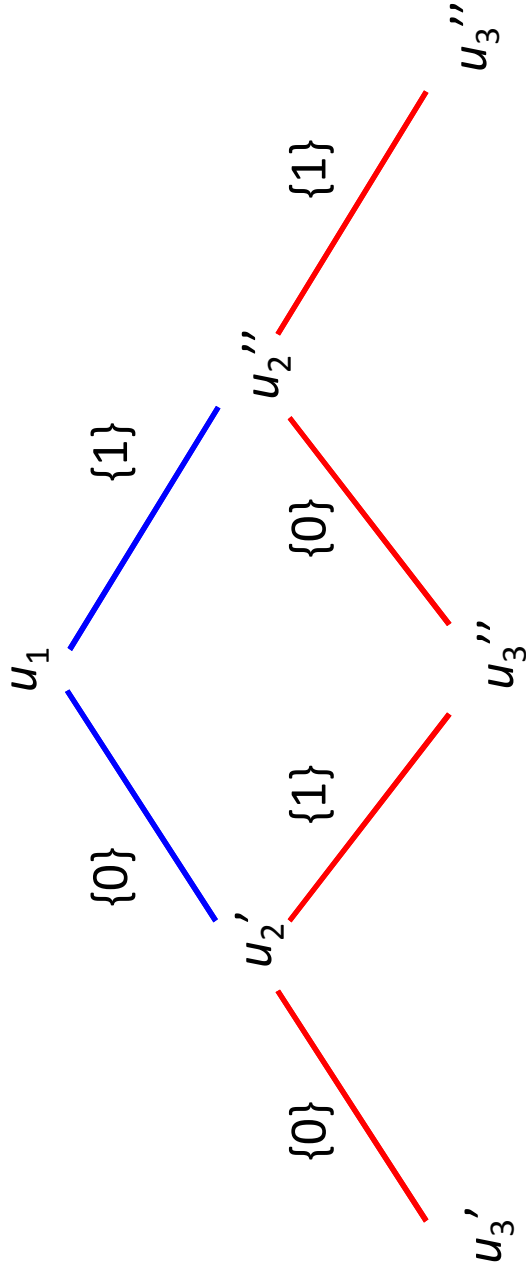
Split? \longrightarrow u_3

Incoming edges partition into 3 equivalence classes, corresponding to path lengths 0, 1, 2

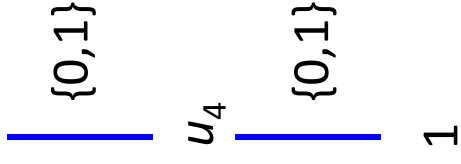


among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example

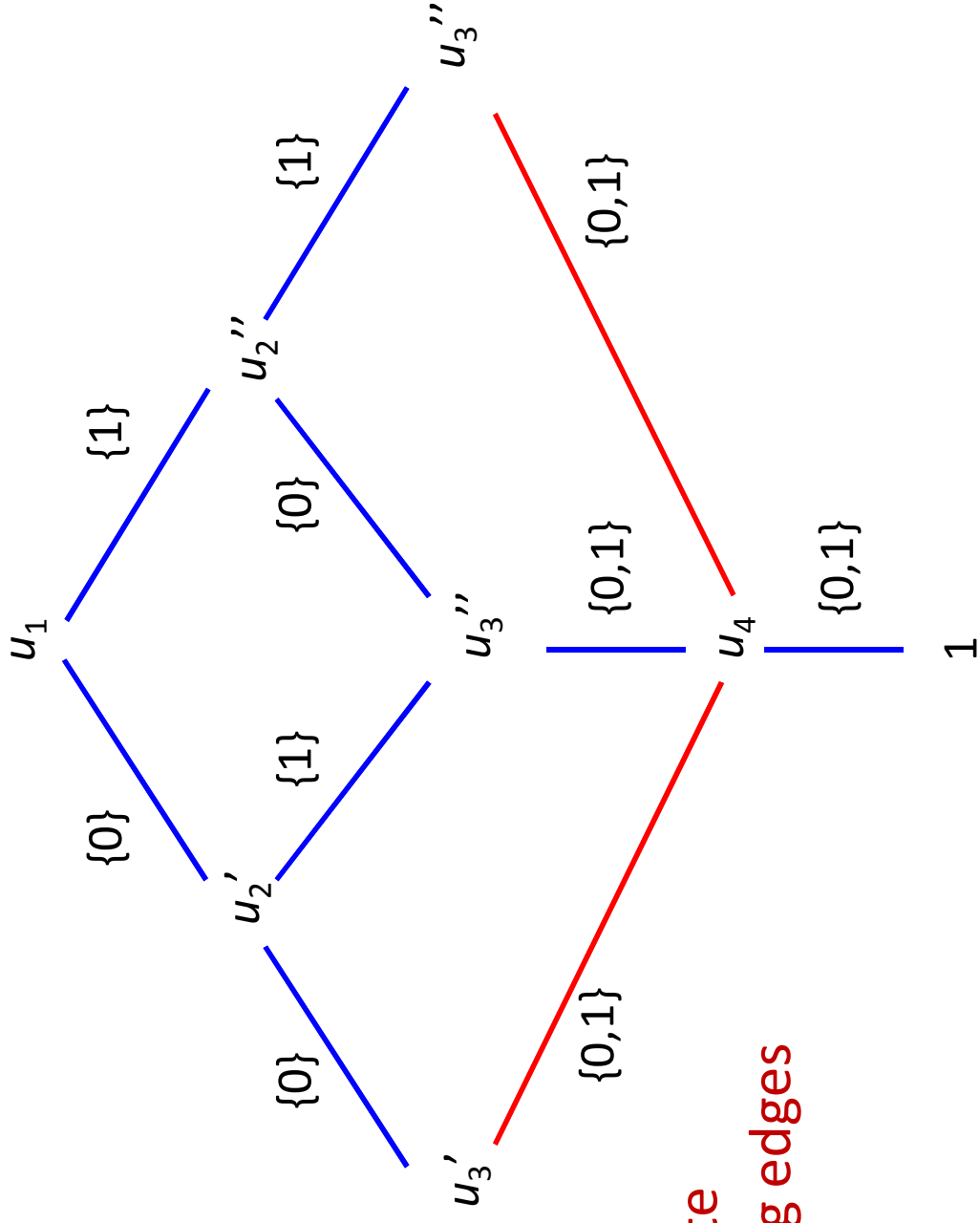


So we split
into 3 nodes



among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

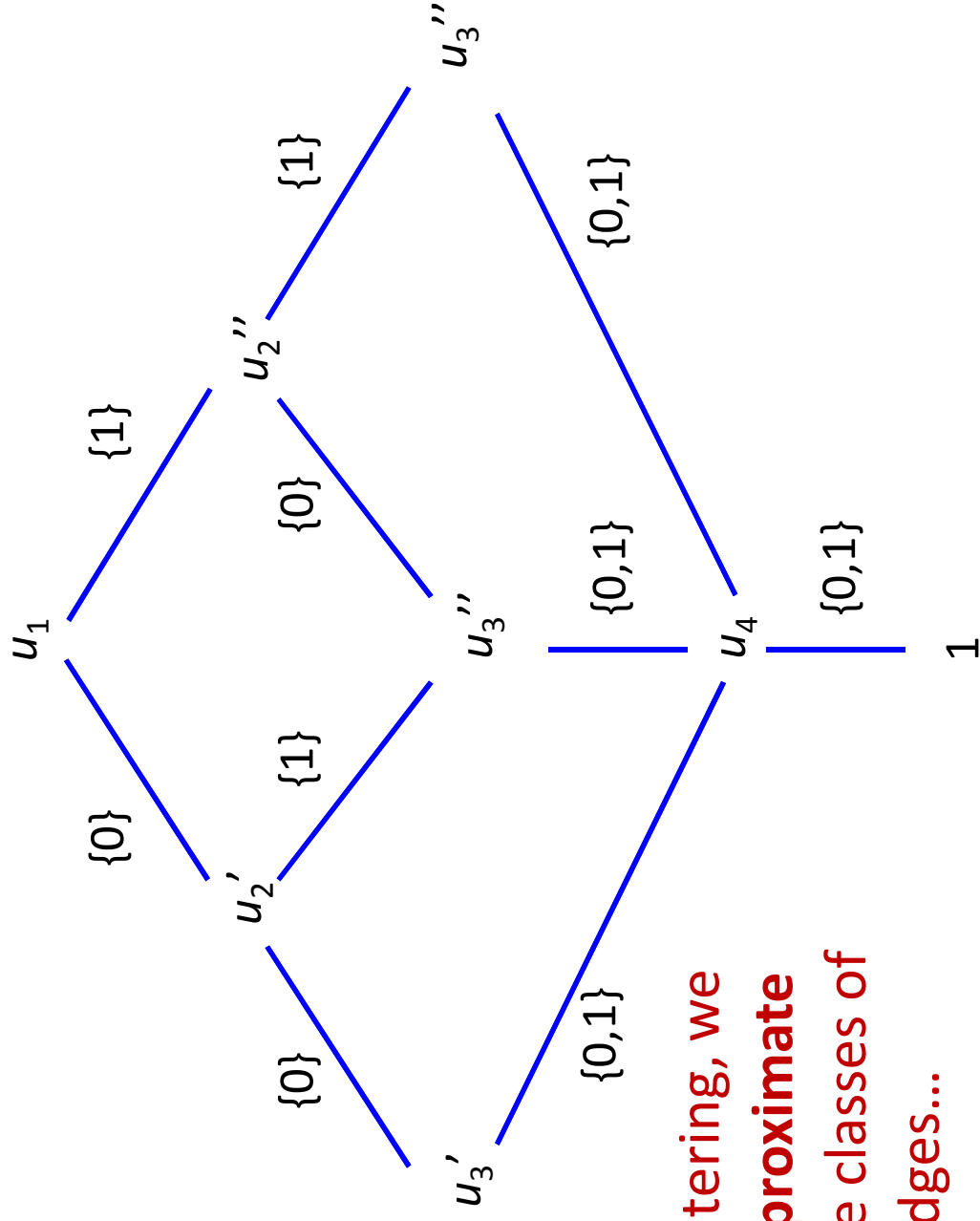
Example



Duplicate
outgoing edges

among($\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$)

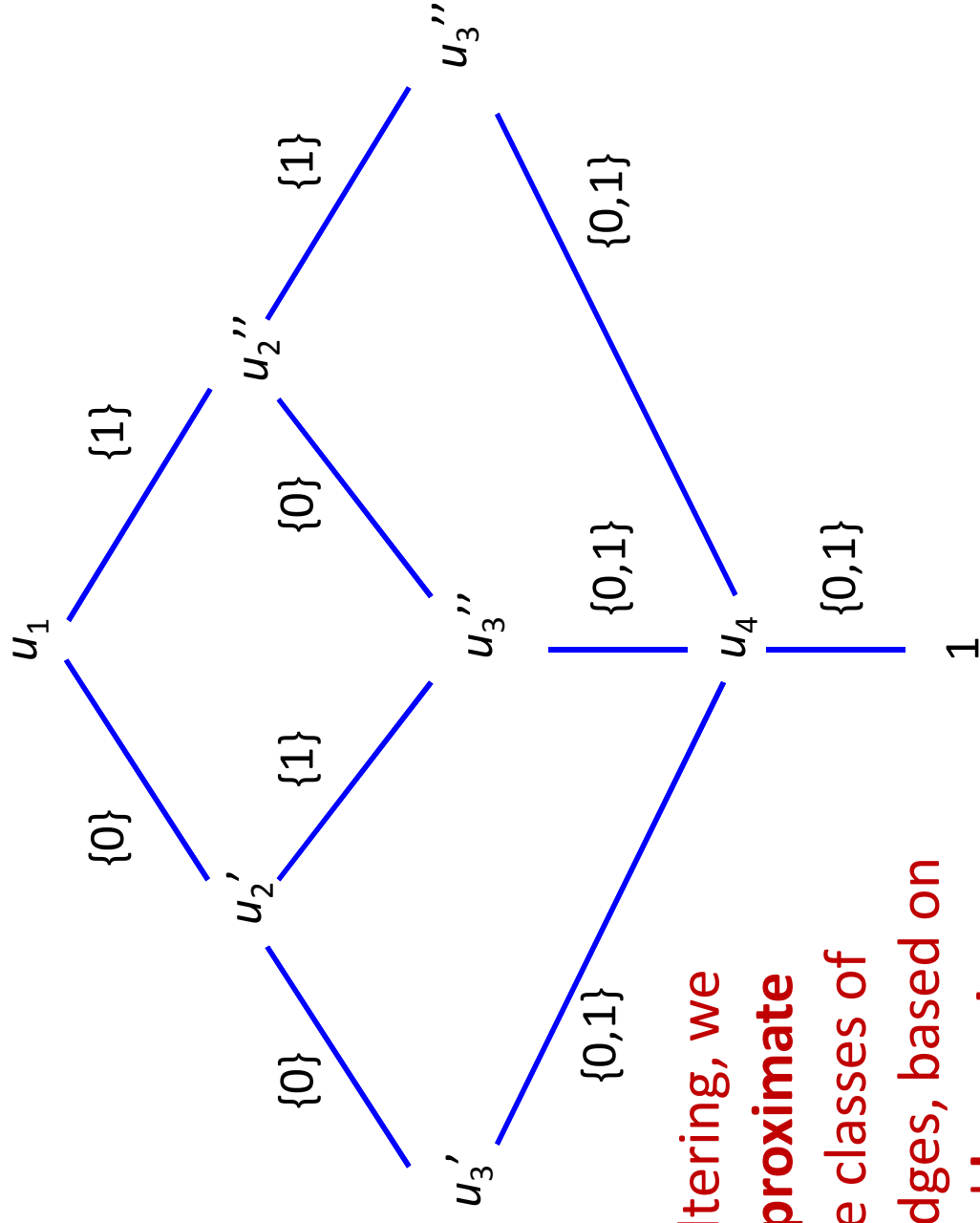
Example



To speed filtering, we identify **approximate** equivalence classes of incoming edges...

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

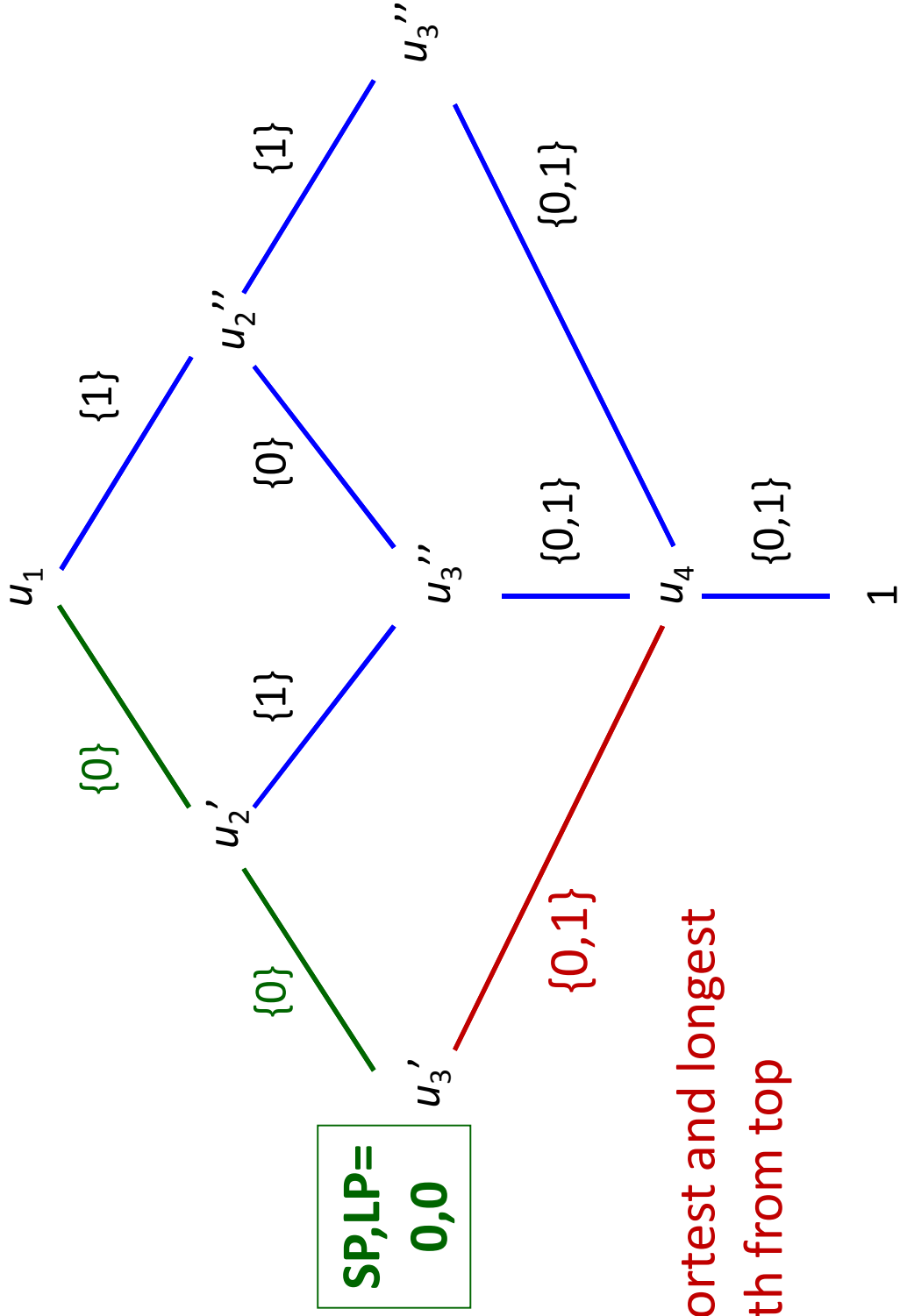
Example



To speed filtering, we identify **approximate** equivalence classes of incoming edges, based on **shortest** and **longest** paths.

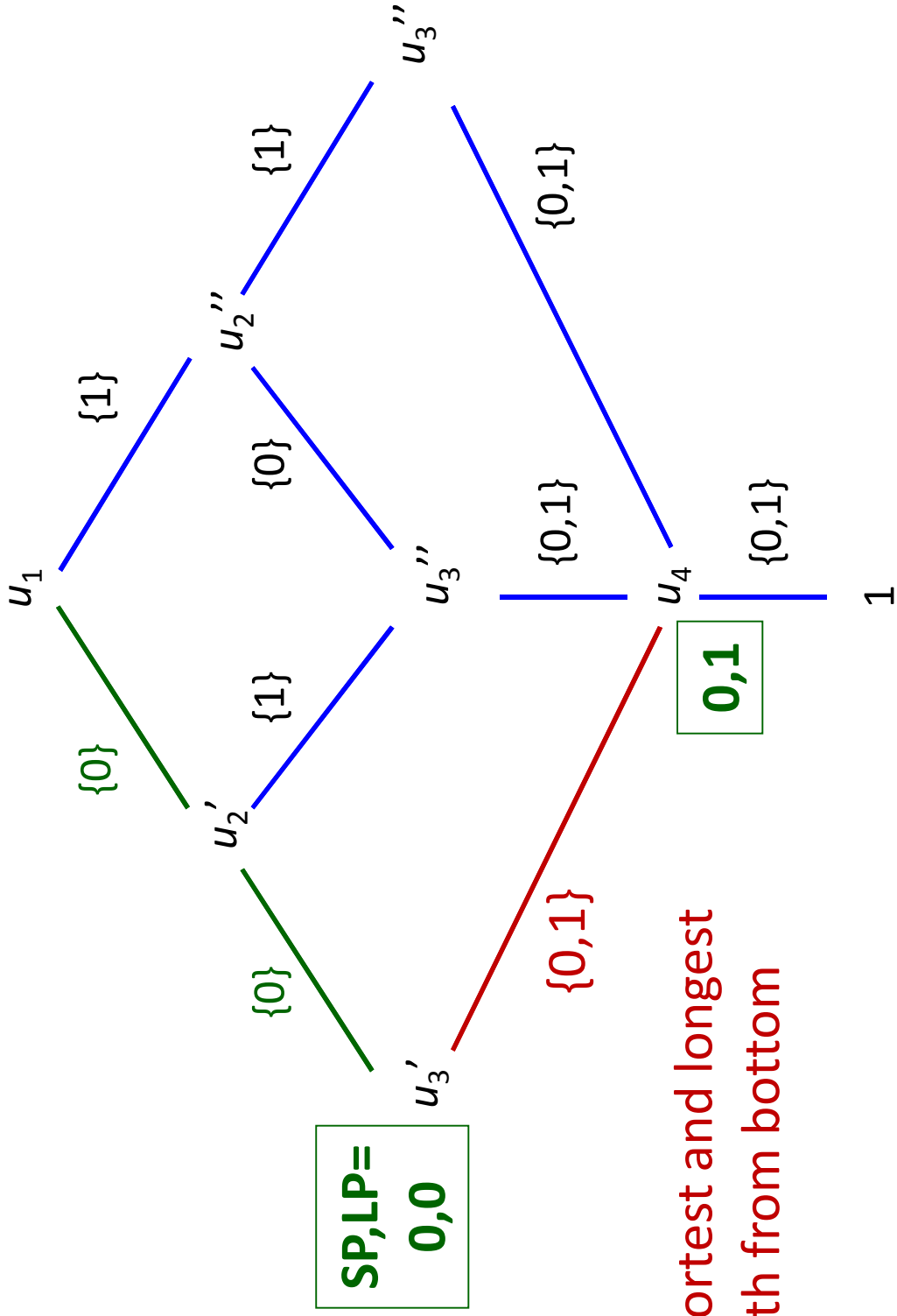
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example



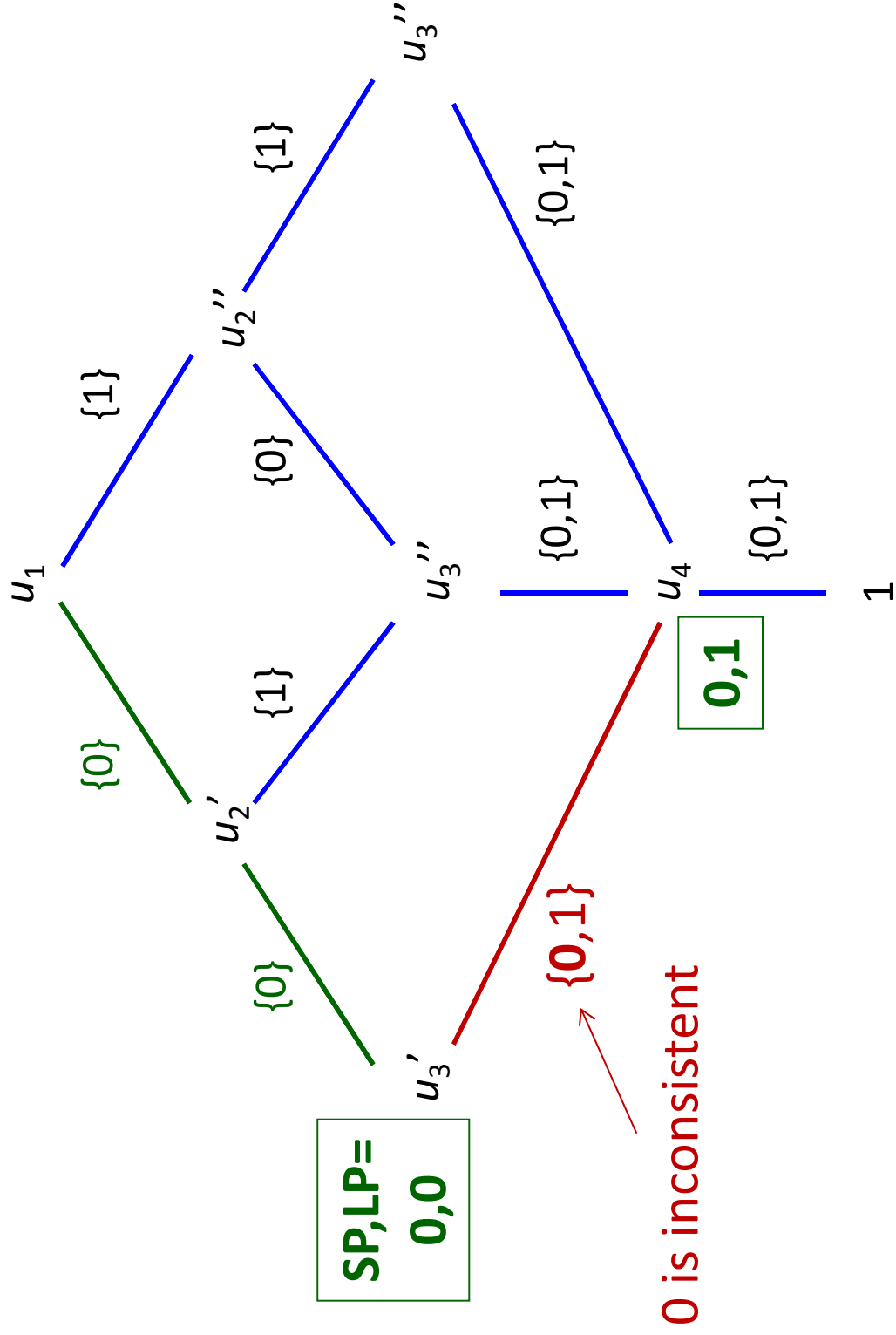
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example



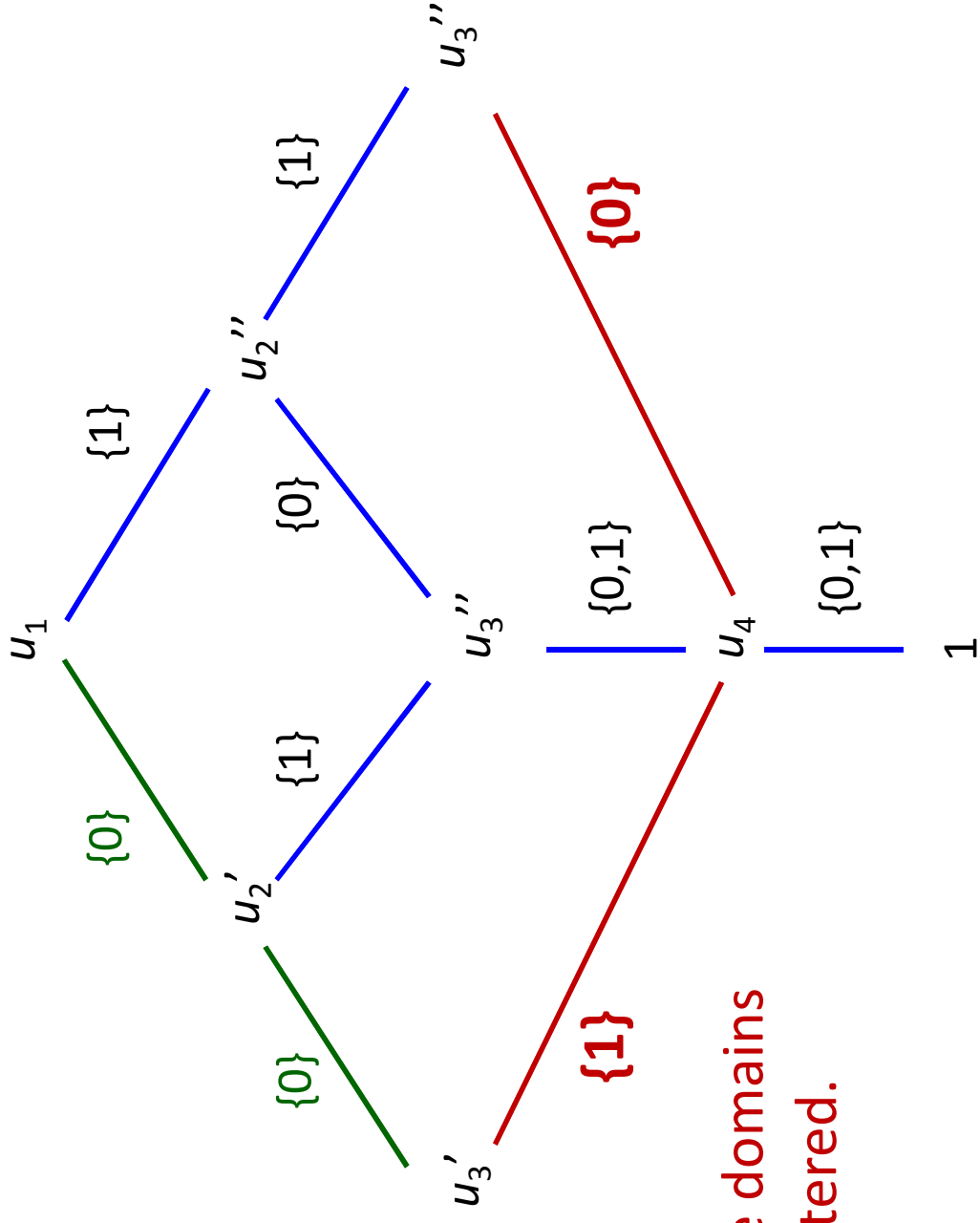
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example



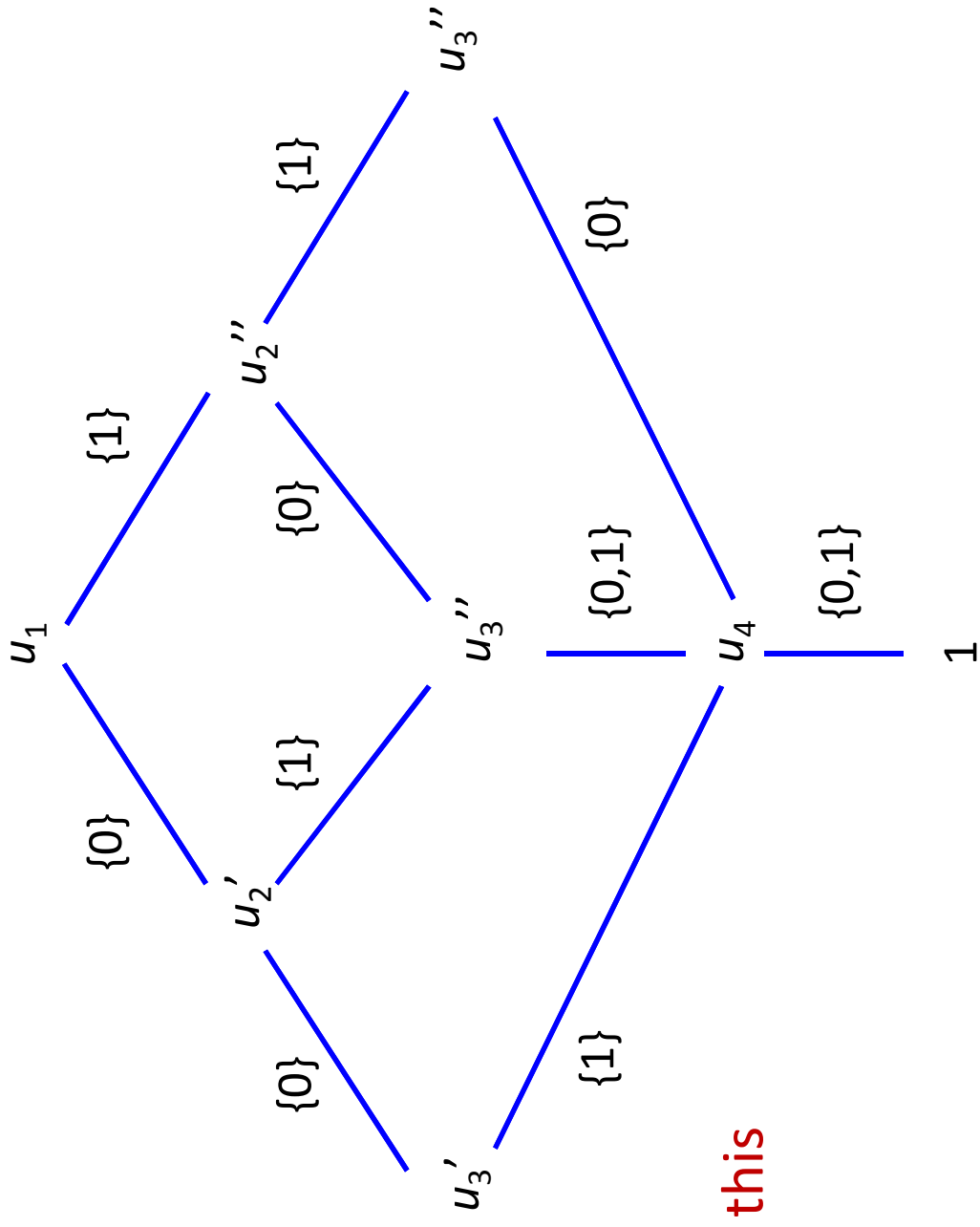
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

Example



among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

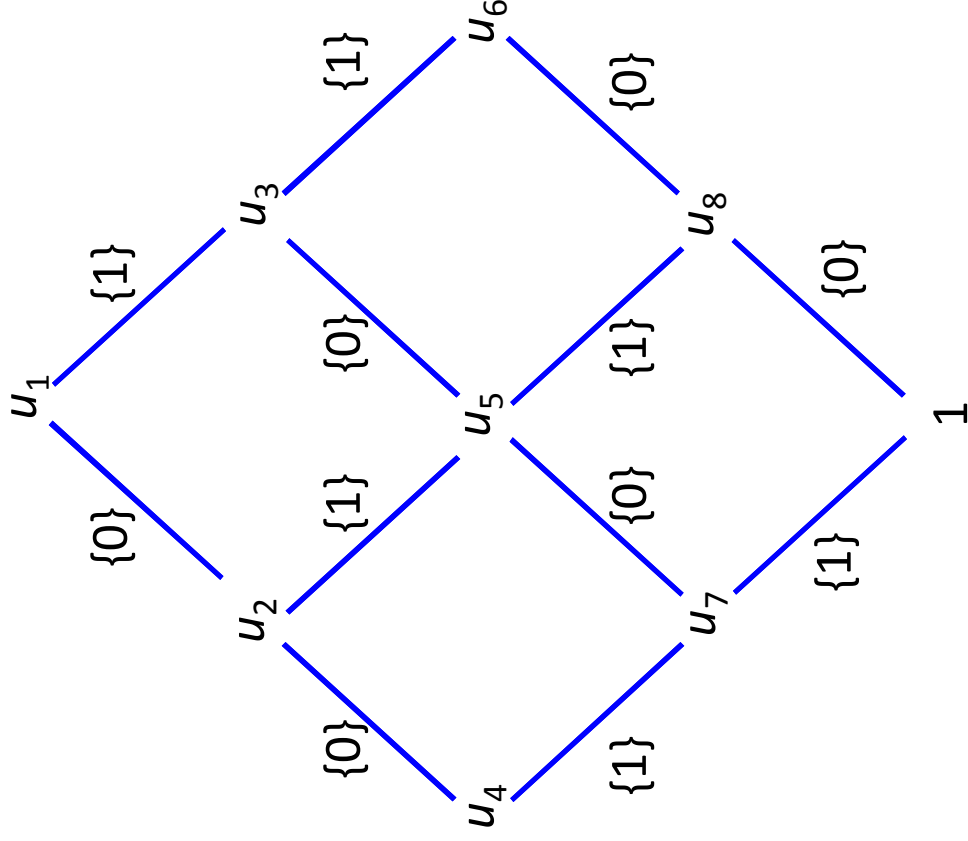
Example



Continue this process...

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

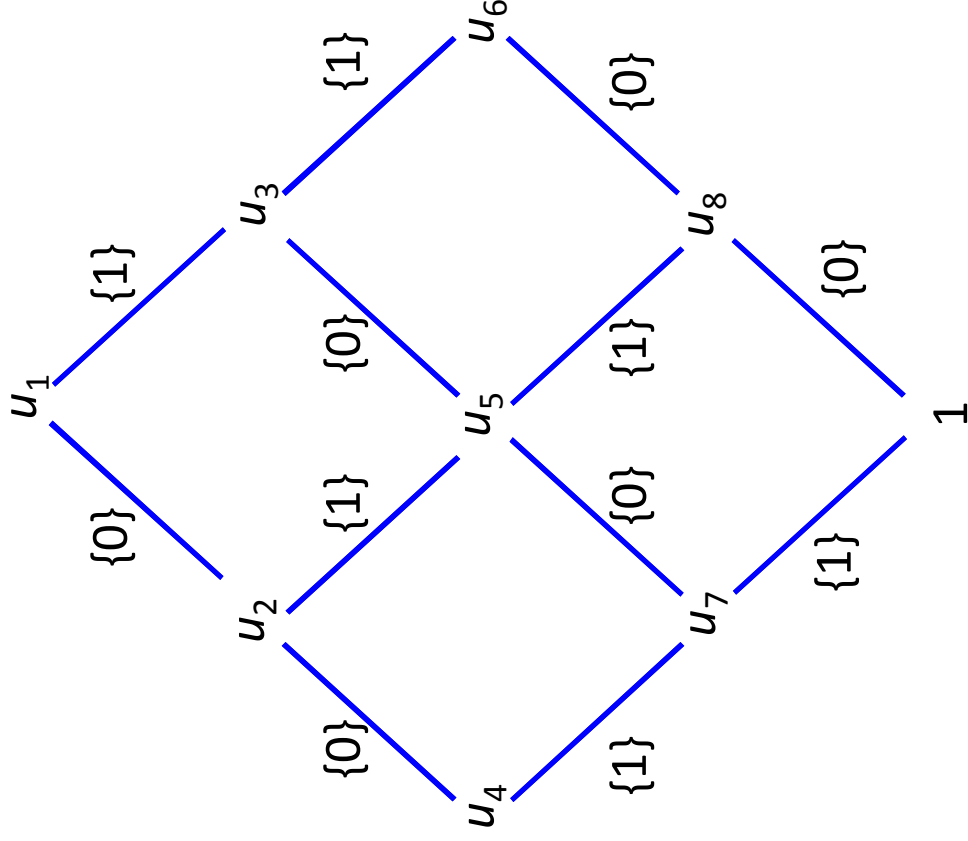
Example



...and obtain a relaxed MDD of width 3

among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

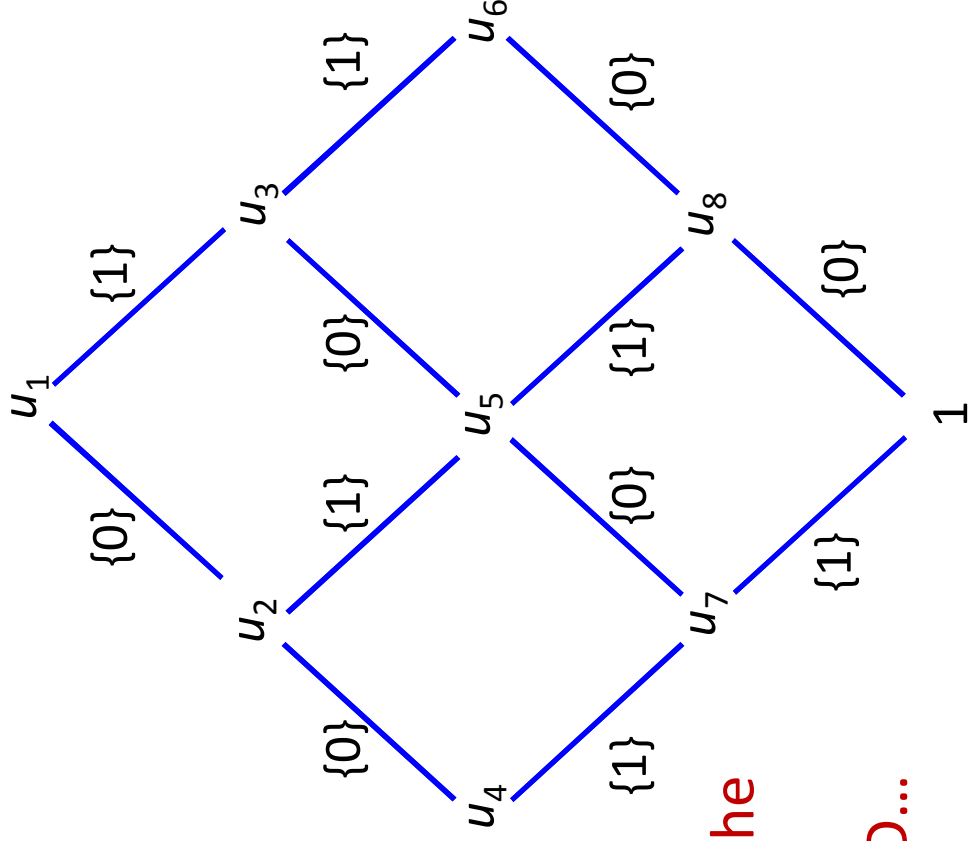
Example



In this case, the MDD is exact.

among $\{x_1, x_2, x_3, x_4\}$, $\{1\}$, $2, 2$

Example



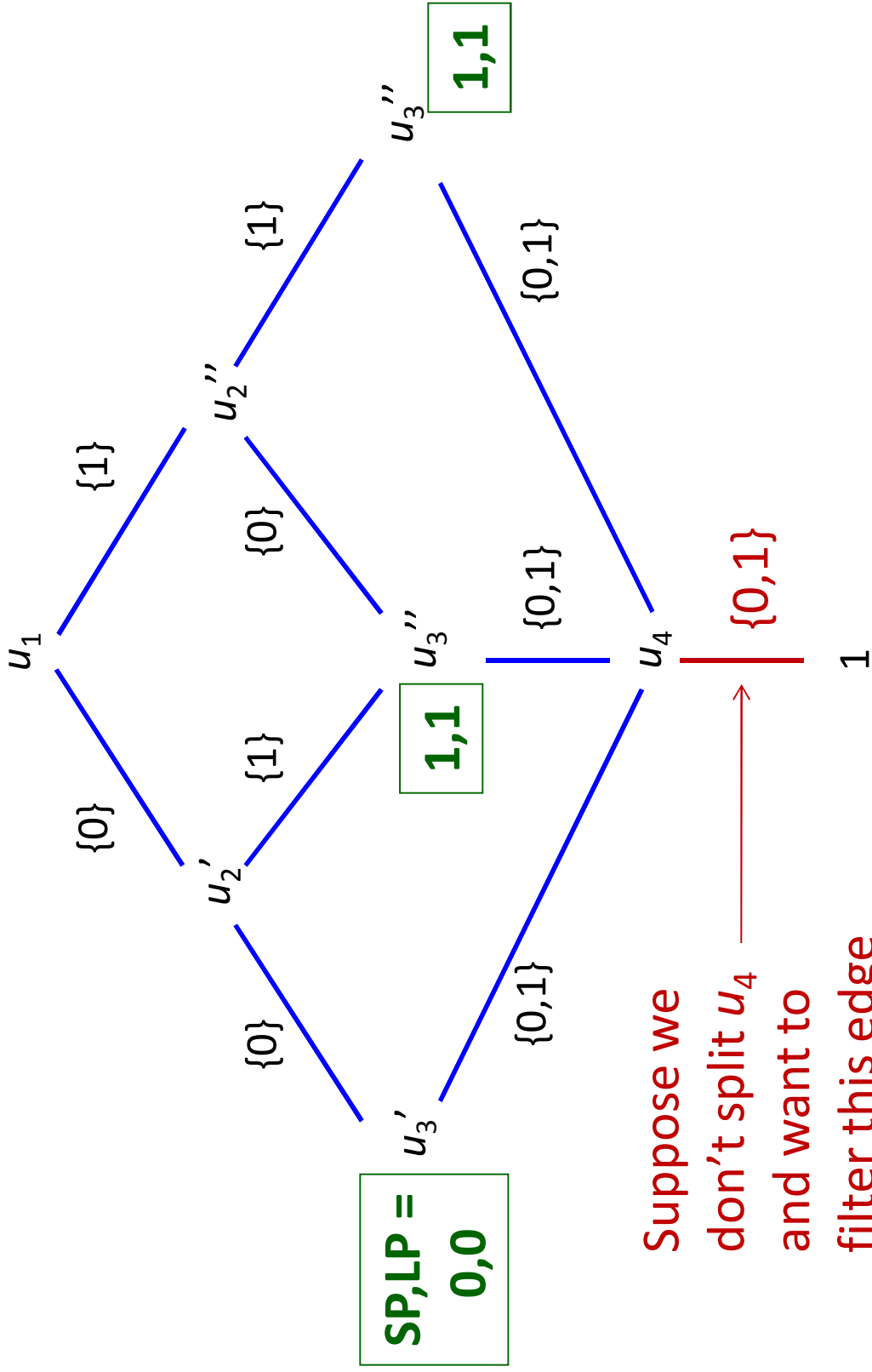
Now, propagate the next constraint through **this** MDD...

among($\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$)

- Identify (approximate) equivalence classes of incoming edges.
- Create a copy of the node for each equivalence class.
 - But without exceeding the max width.
- Duplicate outgoing arcs.
- Method for identifying equivalence classes is **constraint-specific**.
 - This exploits **special structure**.
 - Can also be **dynamic**, e.g. depending on current width.

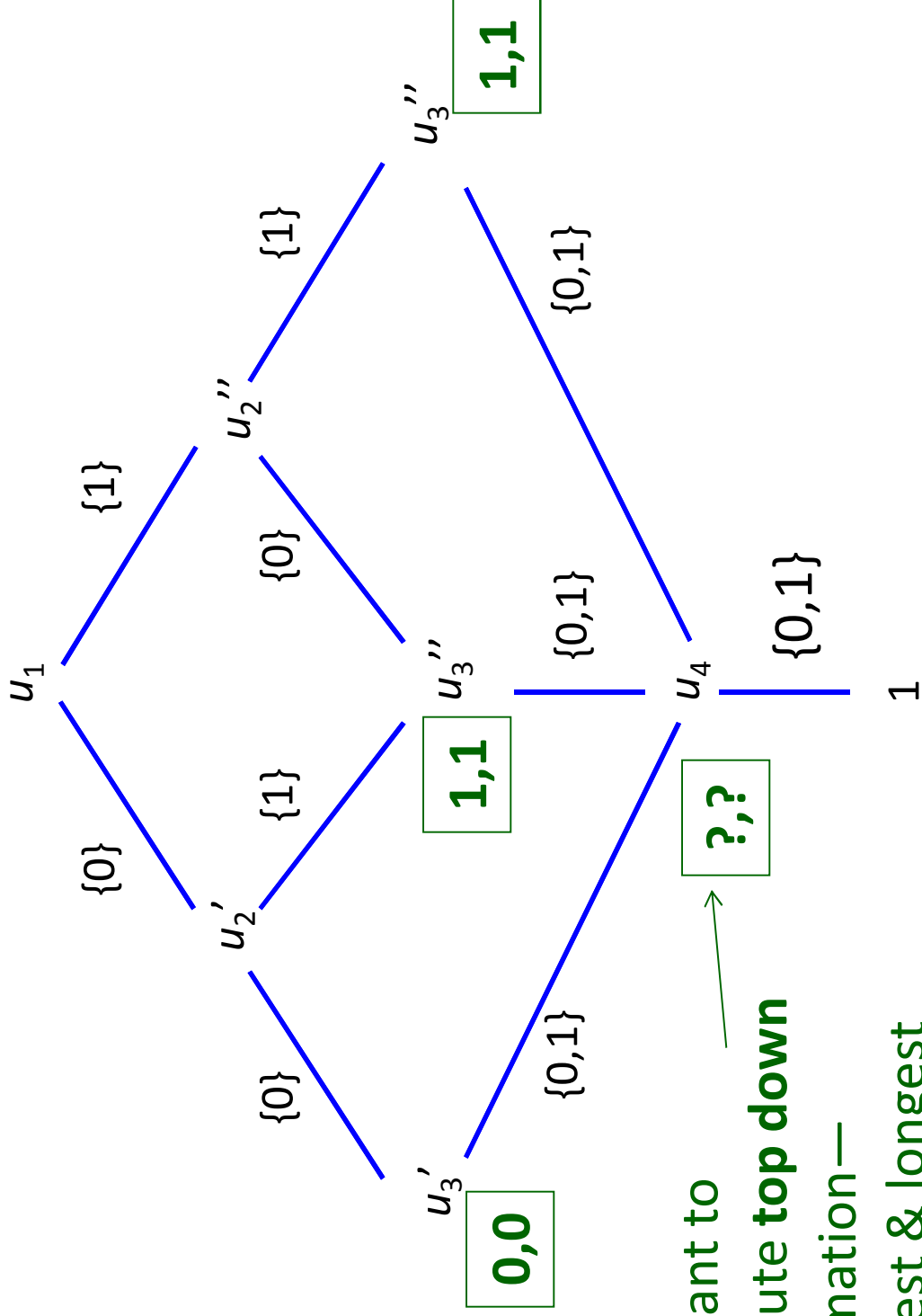
- Filtering on an edge is based on **information** at either end of the edge.
- Information is accumulated during **top-down** and **bottom-up** passes.
 - Based on **extend** (\otimes) and **merge** (\oplus) operations.
- For example...

General Scheme for Filtering



among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

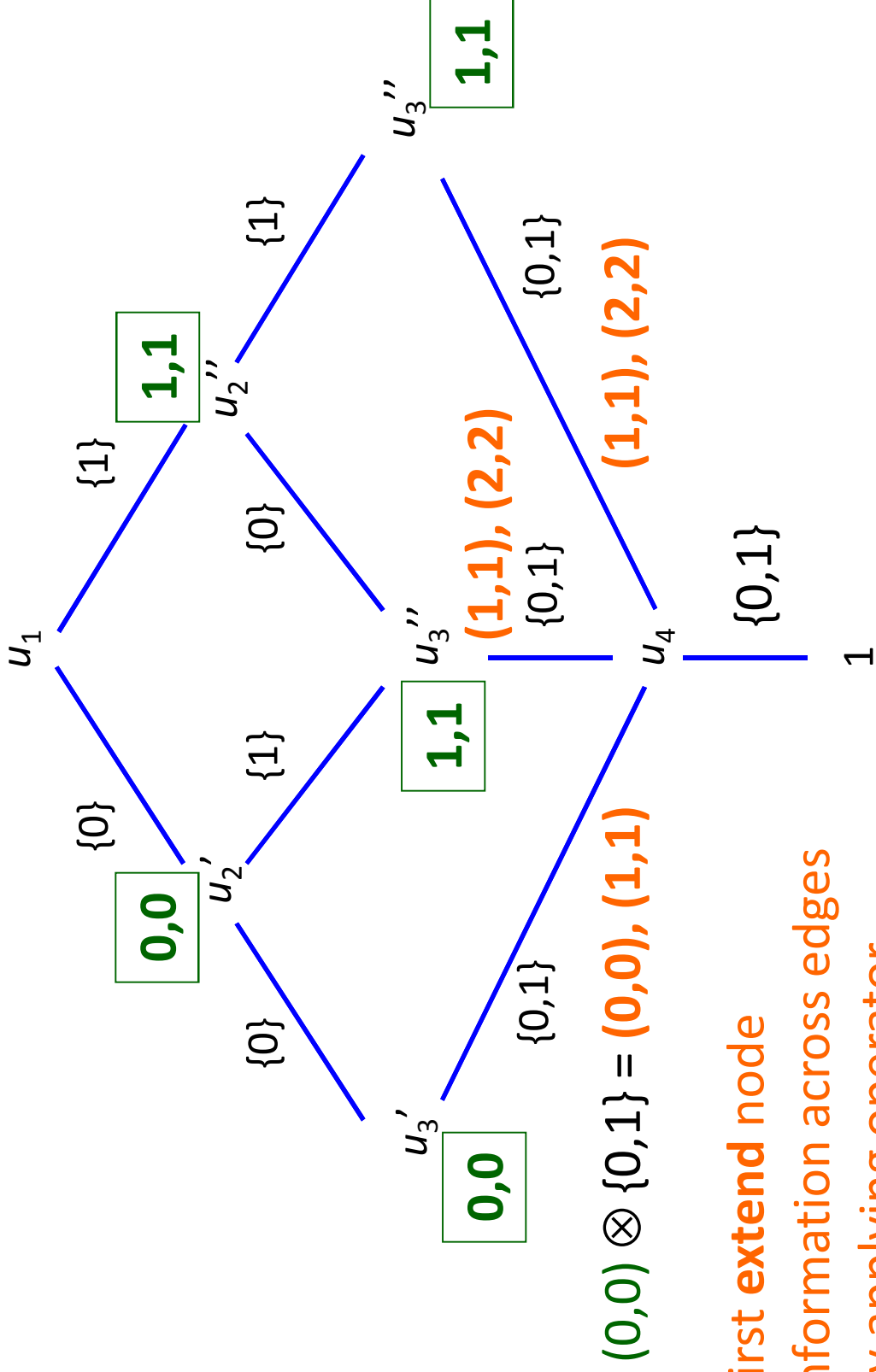
General Scheme for Filtering



We want to compute **top down** information—shortest & longest path length

among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

General Scheme for Filtering

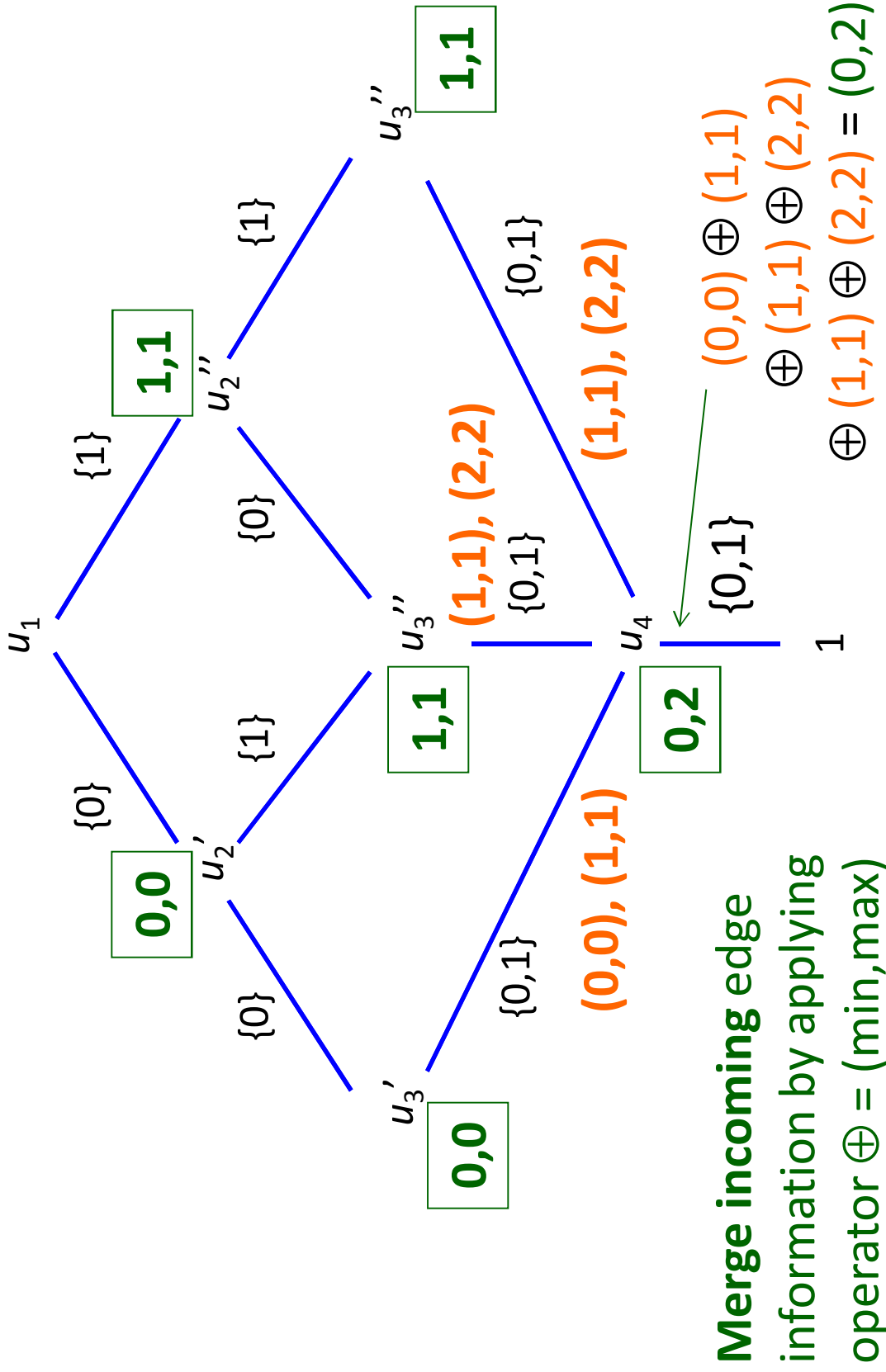


First **extend** node
information across edges
by applying operator

$\otimes = +$

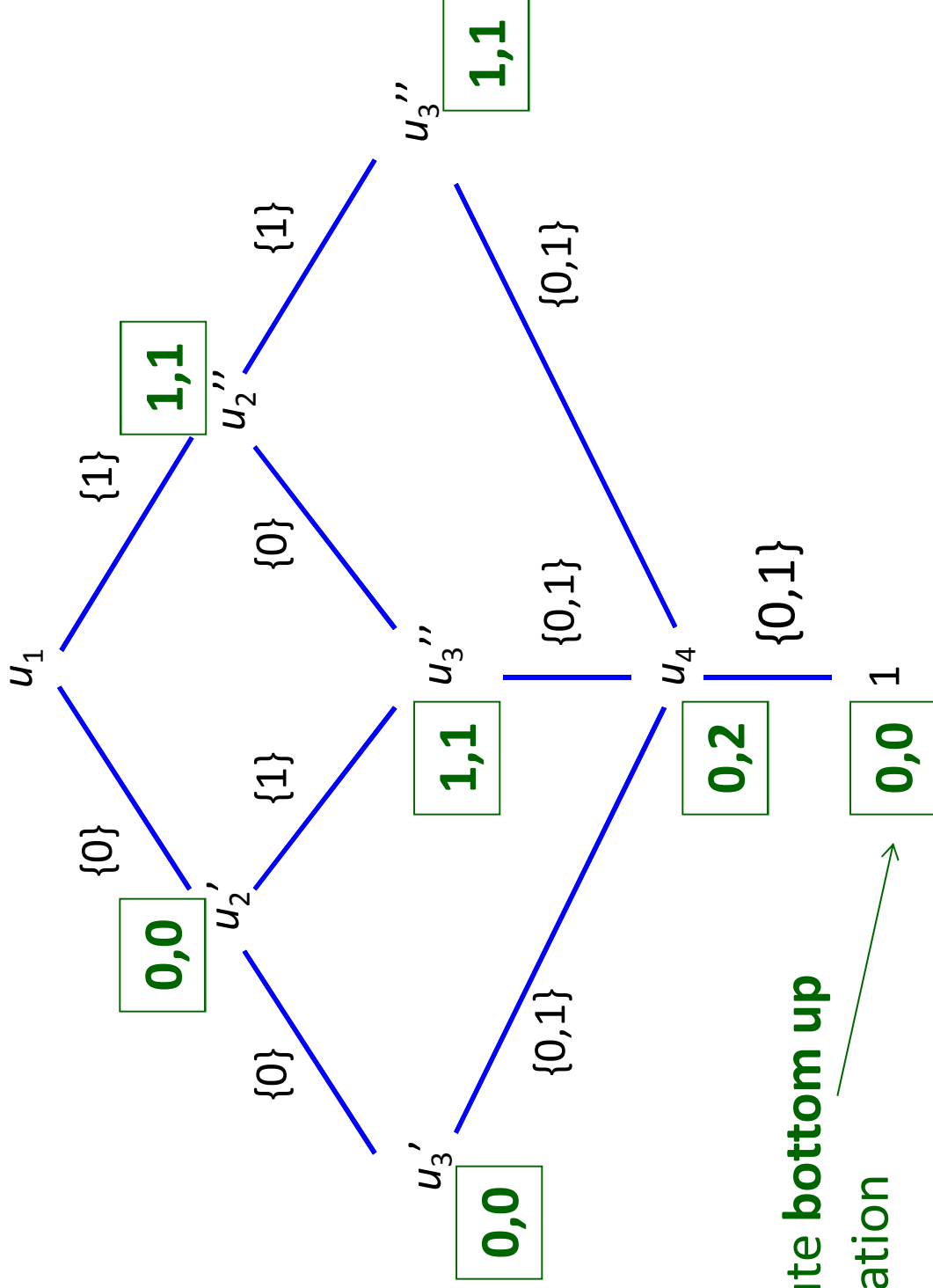
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

General Scheme for Filtering



among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

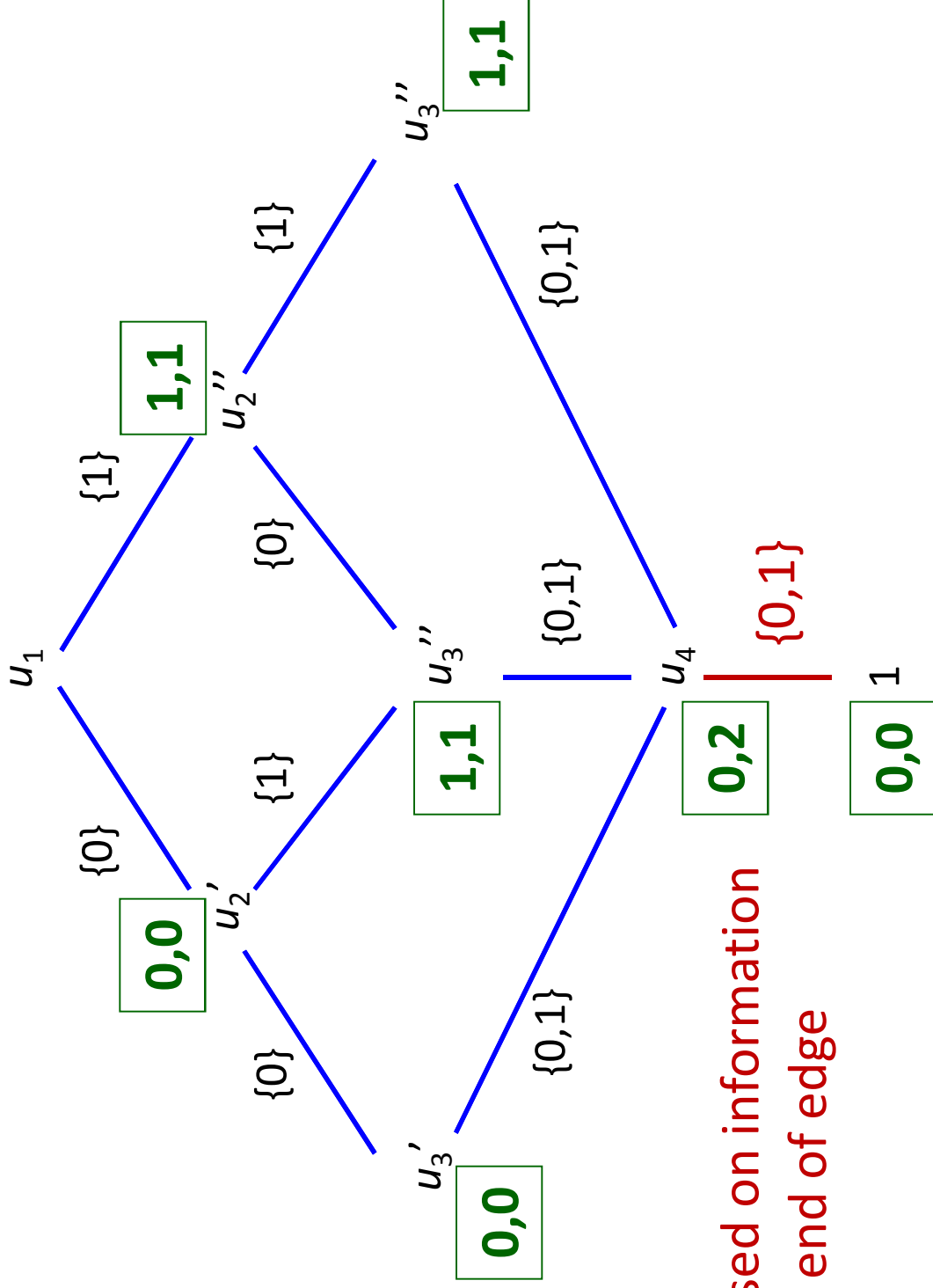
General Scheme for Filtering



Compute **bottom up** information

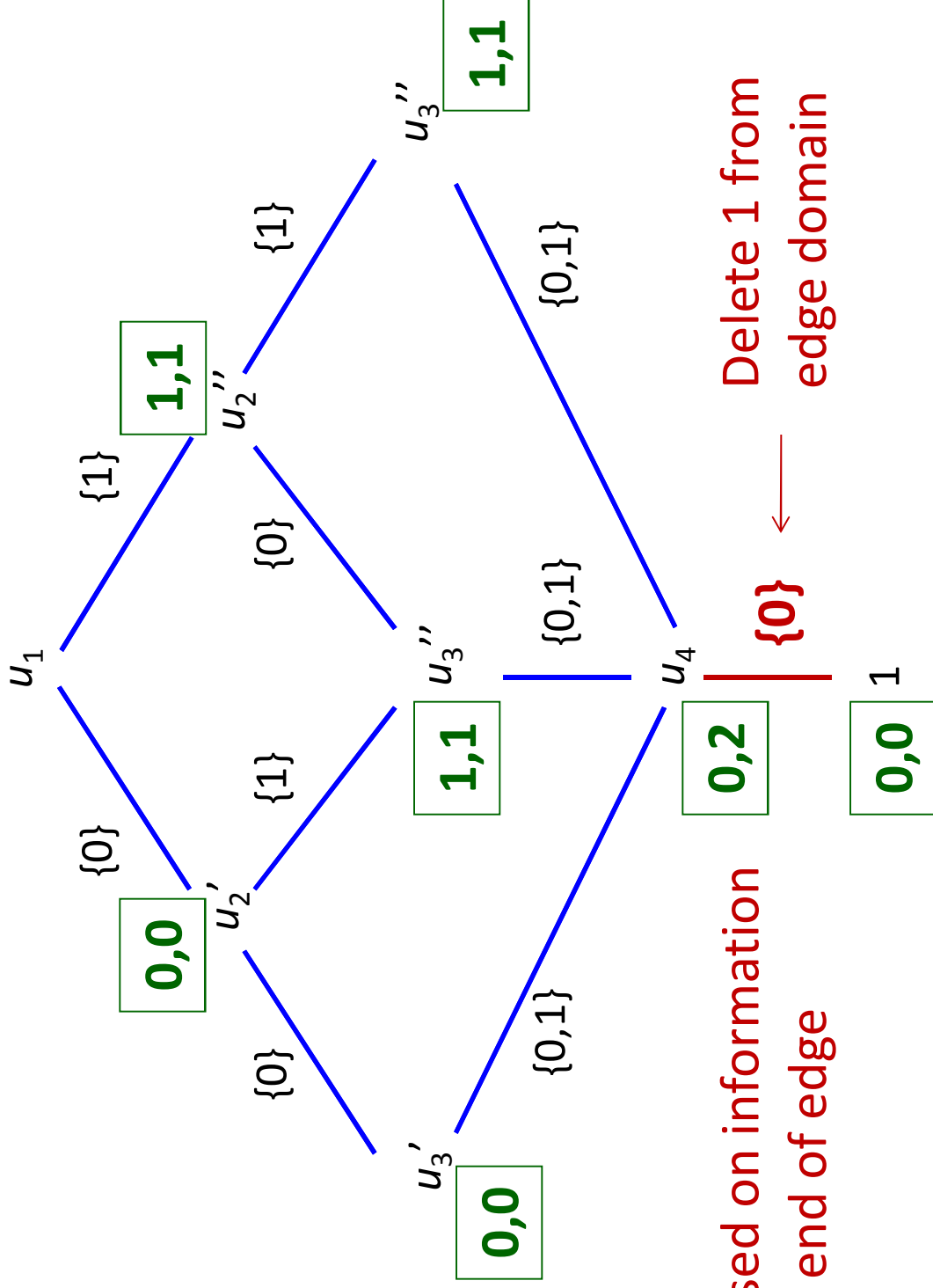
among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

General Scheme for Filtering



among $\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2$

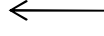
General Scheme for Filtering



among $(\{x_1, x_2, x_3, x_4\}, \{1\}, 2, 2)$

General Scheme for Filtering

X_k u Top down information = (SP,LP)

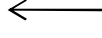


among(X,S,L,U)

Shortest, longest path to u

X_{k+1} u'

Bottom up information = (SP,LP)



Shortest, longest path to u'

General Scheme for Filtering

X_k u Top down information = (SP, LP)

among(X, S, L, U)

{ e }

Delete e if $SP + e + SP' > U$
or $LP + e + LP' < L$

X_{k+1} u' Bottom up information = (SP', LP')

General Scheme for Filtering

X_k u Top down information = (SP, LP)

among(X, S, L, U)

{ e }

Delete e if $SP + e + SP' > U$
or $LP + e + LP' < L$

X_{k+1} u' Bottom up information = (SP', LP')

(SP, LP) \otimes { e } = (SP + e, LP + e)

(SP₁, LP₁) \oplus (SP₂, LP₂)

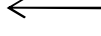
(min{SP₁, SP₂}, max{LP₁, LP₂})

General Scheme for Filtering

X_k u $S = \{\text{all values assigned to } x_j$
on some path to $u\}$

**Any binary
constraint B
with
variables x_i, x_j**

X_{k+1} u' $T = \{\text{all values assigned to } x_j$
on some path to $u'\}$



General Scheme for Filtering

X_k u $S = \{ \text{all values assigned to } x_j \text{ on some path to } u \}$

Any binary constraint B with variables x_i, x_j

Delete e if $k = j$ and $(x_i, x_j) = (v, e)$ satisfies B for no $v \in S$

or $k = i$ and $(x_i, x_j) = (v, e)$ satisfies B for no $v \in T$

X_{k+1} u' $T = \{ \text{all values assigned to } x_j \text{ on some path to } u' \}$

General Scheme for Filtering

X_k u $S = \{\text{all values assigned to } x_j$
 on some path to $u\}$

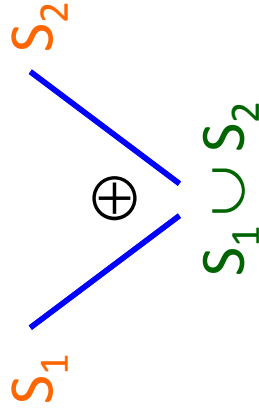
Any binary constraint B
 with variables x_i, x_j

Delete e if $k = j$ and $(x_i, x_j) = (v, e)$ satisfies B
 for no $v \in S$

or $k = i$ and $(x_i, x_j) = (v, e)$ satisfies B
 for no $v \in T$

$T = \{\text{all values assigned to } x_j$
 on some path to $u'\}$

$S \otimes \{e\} = \{e\}$ if $k = i$, S otherwise



**Any binary
constraint B**
with
variables x_i, x_j

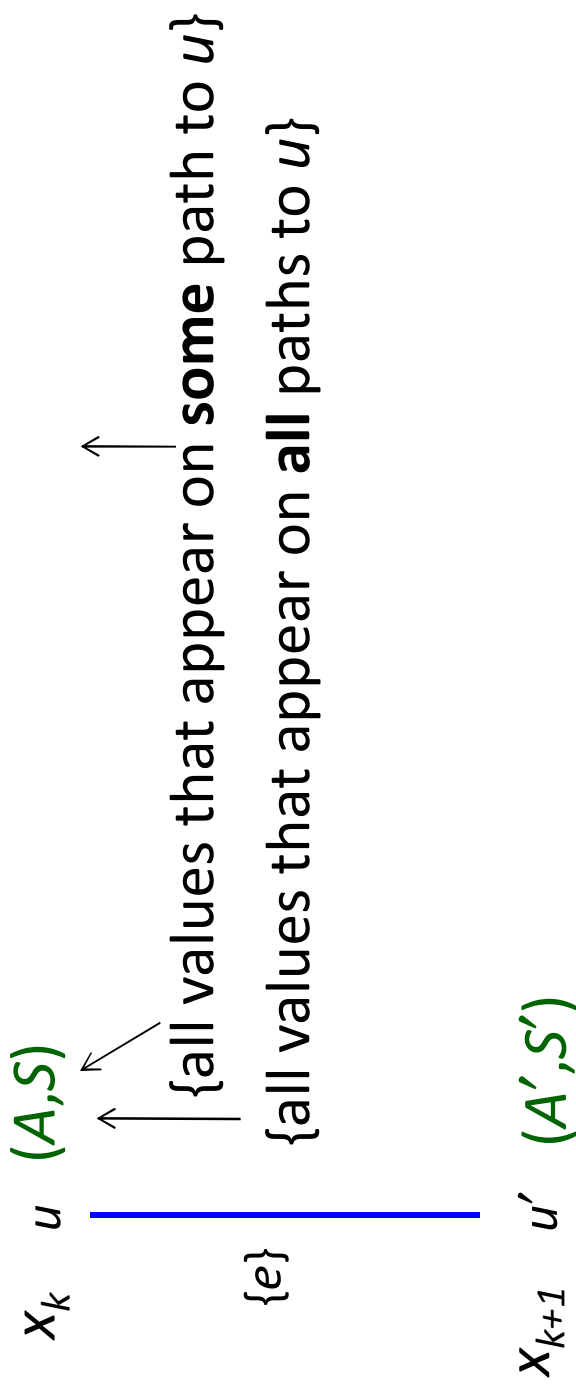
Theorem. This scheme achieves MDD
consistency for any binary constraint B
in time that is polynomial in size of B
and the MDD.

Any binary constraint B
with
variables x_i, x_j

Theorem. This scheme achieves MDD consistency for any binary constraint B in time that is polynomial in size of B and the MDD.

Corollary. Polytime MDD consistency for:
equality, not-equal constraints, element constraint,
etc.

General Scheme for Filtering



alldiff(x)

General Scheme for Filtering

X_k u (A, S)

alldiff(x)

$\{e\}$

Delete e if $e \in A \cup A'$, or:

$|S| = k - 1$ or $|S'| = n - k$

(variables above or below form a Hall set)

X_{k+1} u' (A', S')

$X_k \quad u \quad (A, S)$

alldiff(x)

$\{e\}$

Delete e if $e \in A \cup A'$, or:

$|S| = k - 1$ or $|S'| = n - k$

(variables above or below form a Hall set)

$X_{k+1} \quad u' \quad (A', S')$

$(A, S) \otimes \{e\} = (A \cup \{e\}, S \cup \{e\})$

$(A_1, S_1) \quad \oplus \quad (A_2, S_2)$

$(A_1 \cap A_2, S_1 \cup S_2)$

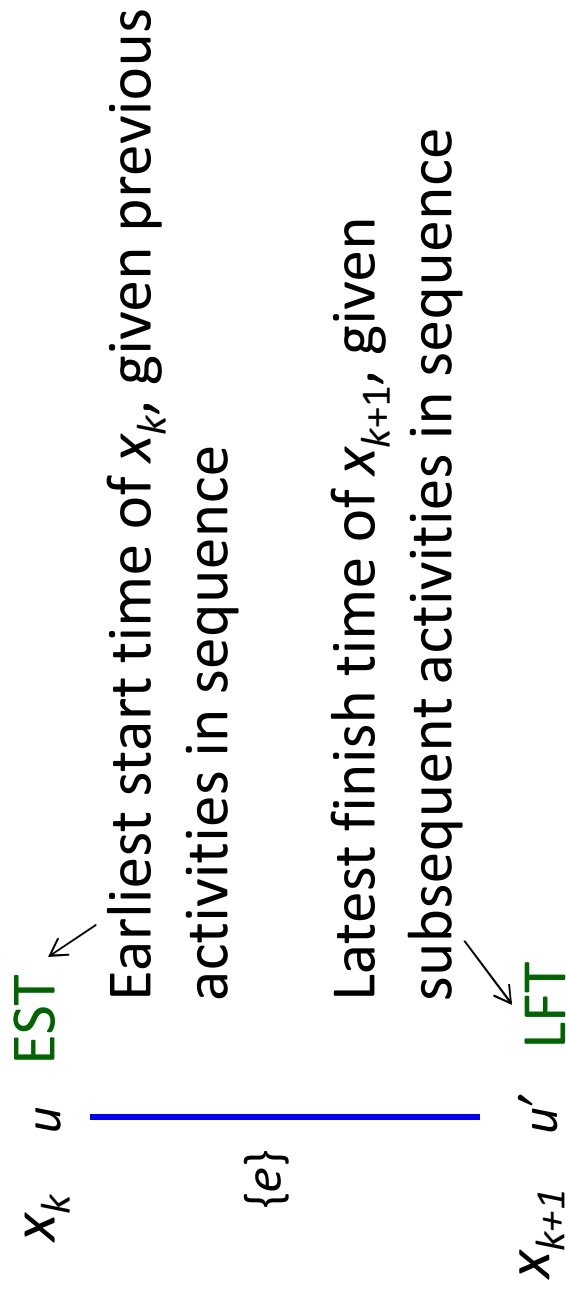
General Scheme for Filtering

Unary resource constraint

x_i = activity in position i of sequence

r_i, d_i = release time, deadline

Enforce `allDiff(X)`
plus:



General Scheme for Filtering

Unary resource constraint

X_k u **EST**

x_i = activity in position i of sequence

{ e }

Delete e if $\max\{\text{EST}, r_e\} + p_e > \min\{\text{LFT}, d_e\}$

r_i, d_i = release time, deadline

X_{k+1} u' **LFT**

Enforce `allDiff(X)`
plus:

General Scheme for Filtering

Unary resource constraint

X_k u **EST**

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X_{k+1} u' **LFT**

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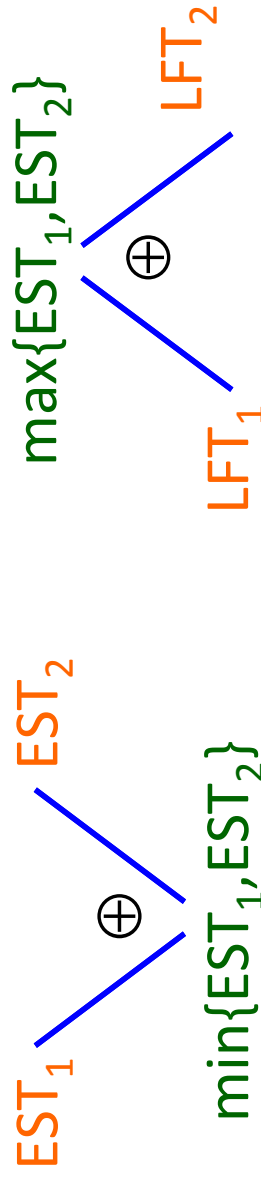
$$\text{EST} \otimes \{e\} = \max\{\text{EST} + p_e, r_e + p_e\}$$

$$\text{LFT} \otimes \{e\} = \min\{\text{LFT} - p_e, d_e - p_e\}$$

Enforce

$\text{allDiff}(X)$

plus:



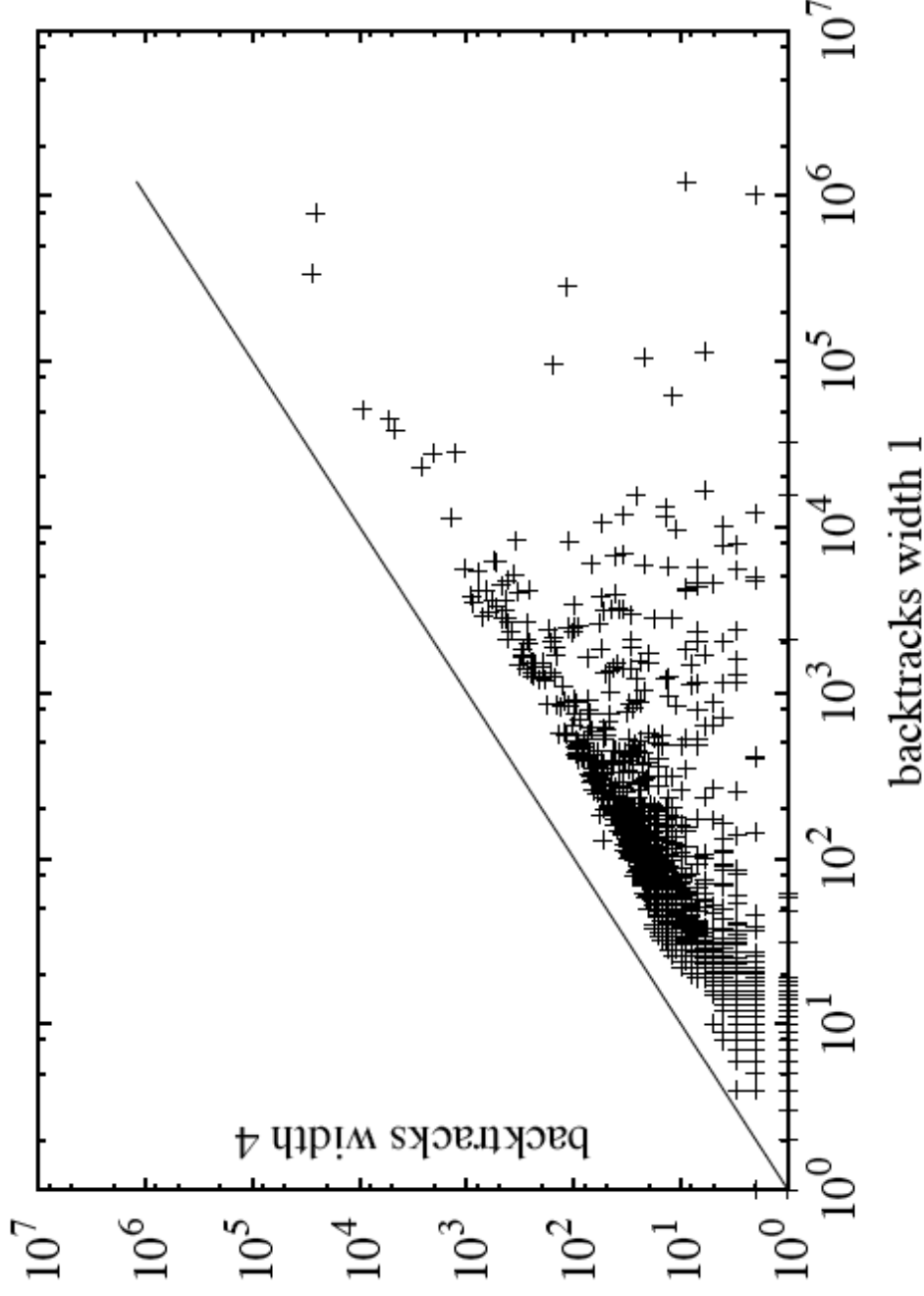
- Our MDD-based solver is built around this general scheme for splitting and filtering.
- Plug in constraint-specific (approximate) equivalence test for splitting.
- Plug in constraint-specific \otimes , \oplus for filtering.

- Multiple alldiff constraints
 - Andersen et al., CP 2007
 - MDDs of width 5
 - Reduce search tree of 1 million+ nodes to 1 node.
 - Reduce time by factor of 30
 - Using old software
- Equality constraints $\sum_j g_j(x_j) = b$
 - Hadzic et al., CPAIOR 2008
- Certain configuration problems
 - Hadzic et al., CP 2008

- Random multiple among constraints
- Nurse rostering instances
- Compare domain store (conventional filtering) with MDD store
 - Using MDDs of increasing widths.

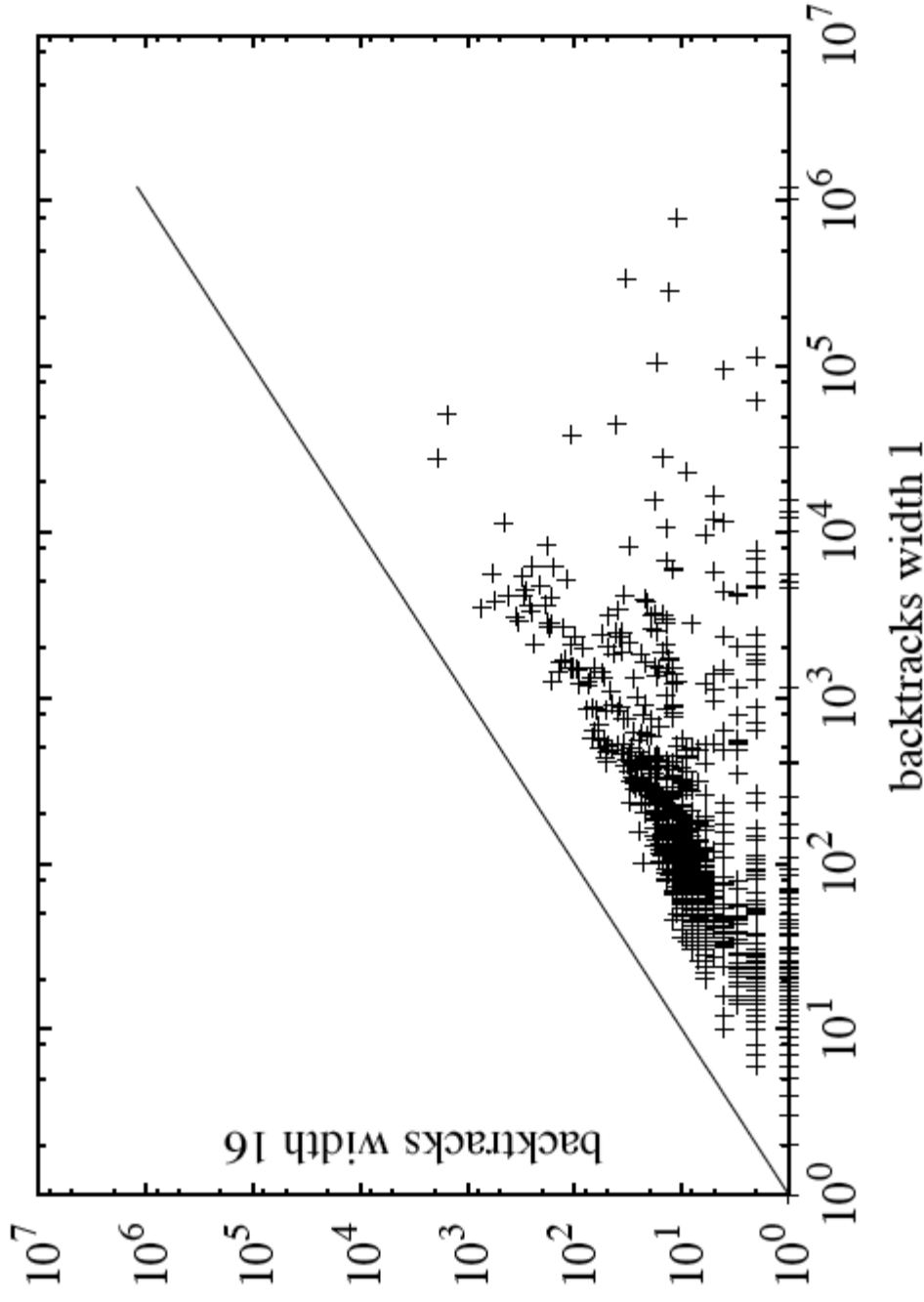
- Random multiple among constraints
 - 50 binary variables total
 - 5 variables per among constraint
 - Indices chosen from normal distribution with mean chosen from $U[1..50]$ mod 50, and standard deviation 2.5
 - So, indices in a given among are near-consecutive, typical of applications.
 - $(L,U) = (2,3)$
 - Number of amongs varies from 5 to 200 (in steps of 5), 100 instances for each number.
 - This range includes phase transition.

Multiple Amongs: Backtracks



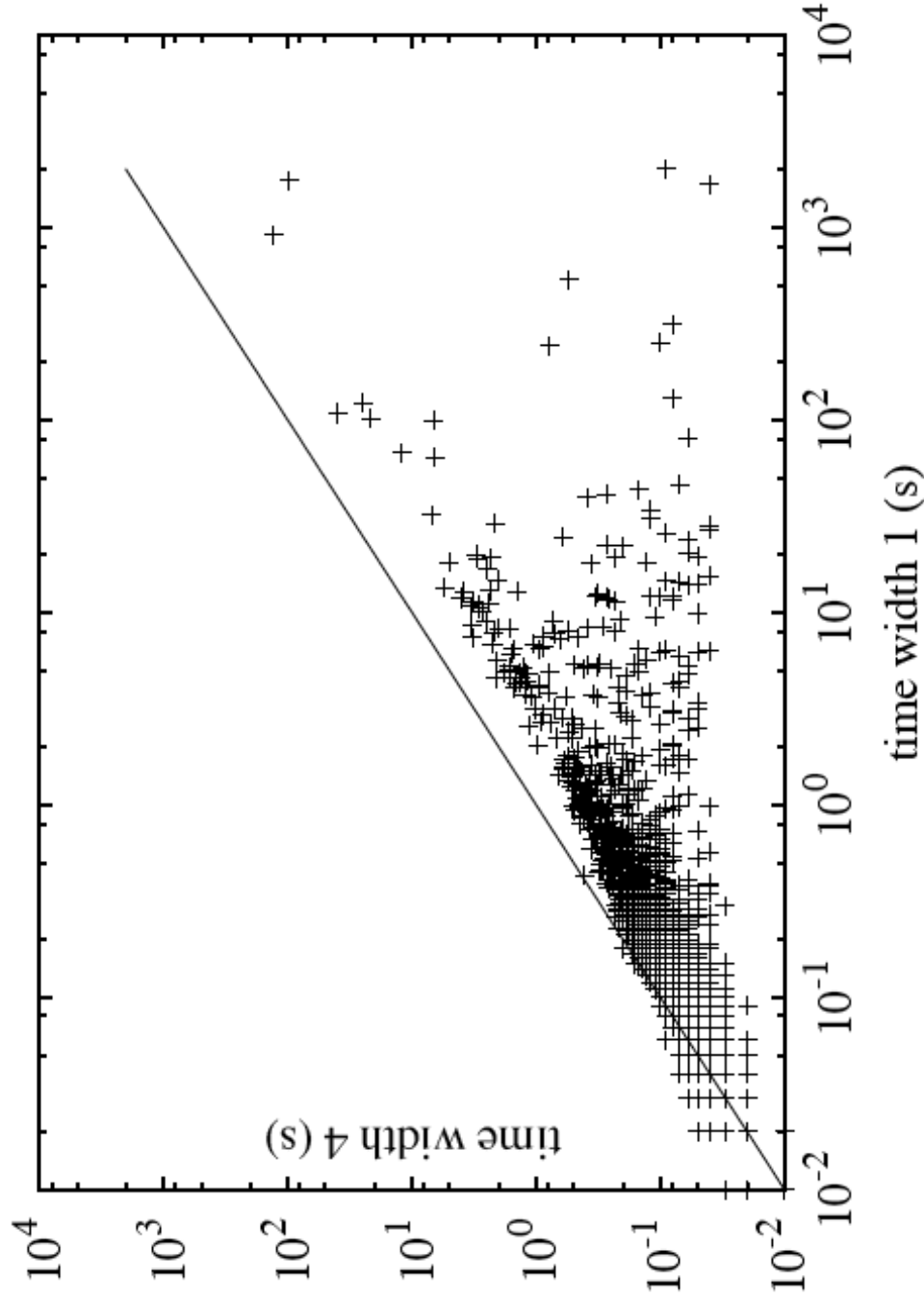
Domain store vs width 4 MDD

Multiple Amongs: Backtracks



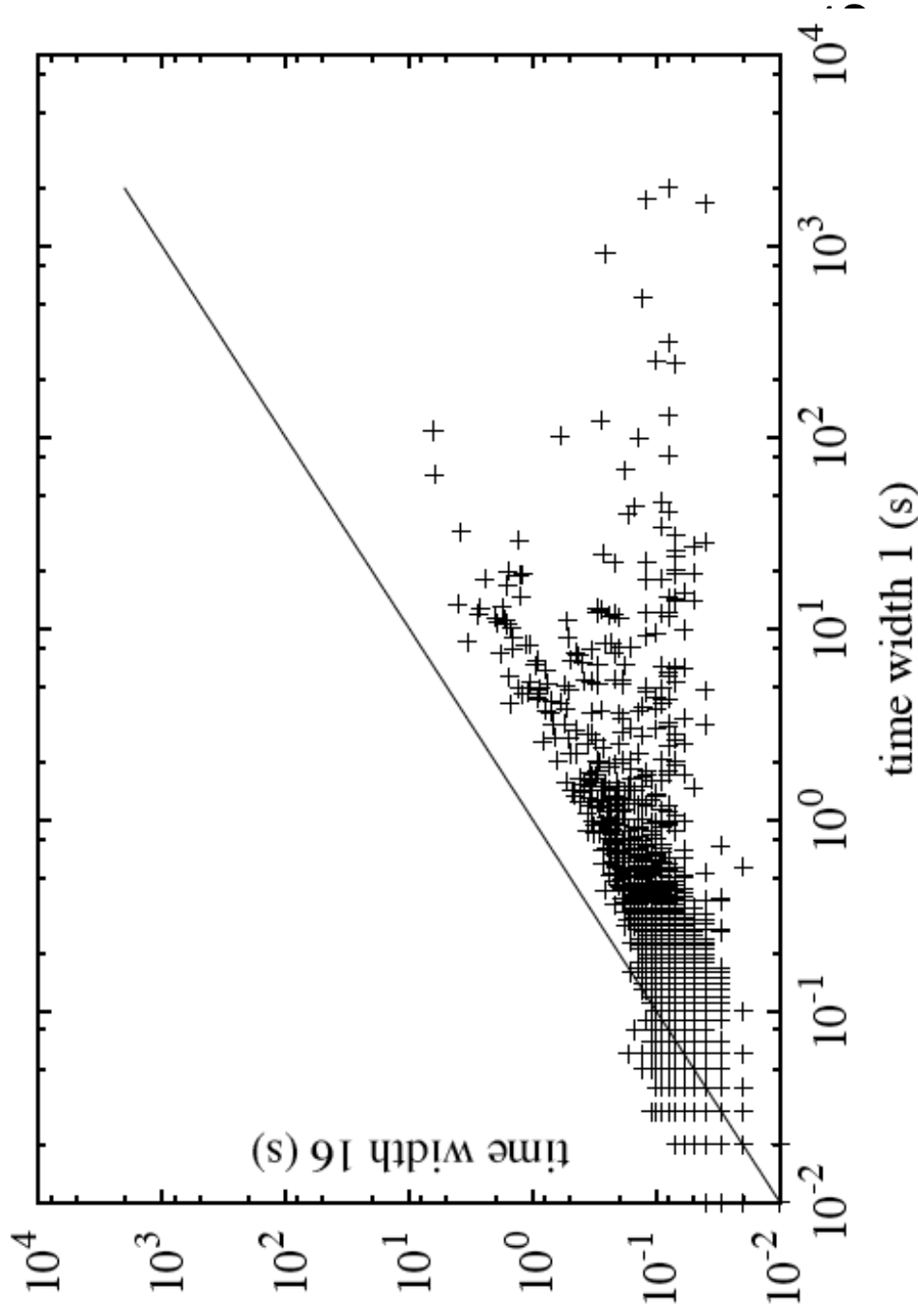
Domain store vs width **16** MDD

Multiple Amongs: Running Time



Domain store vs width 4 MDD

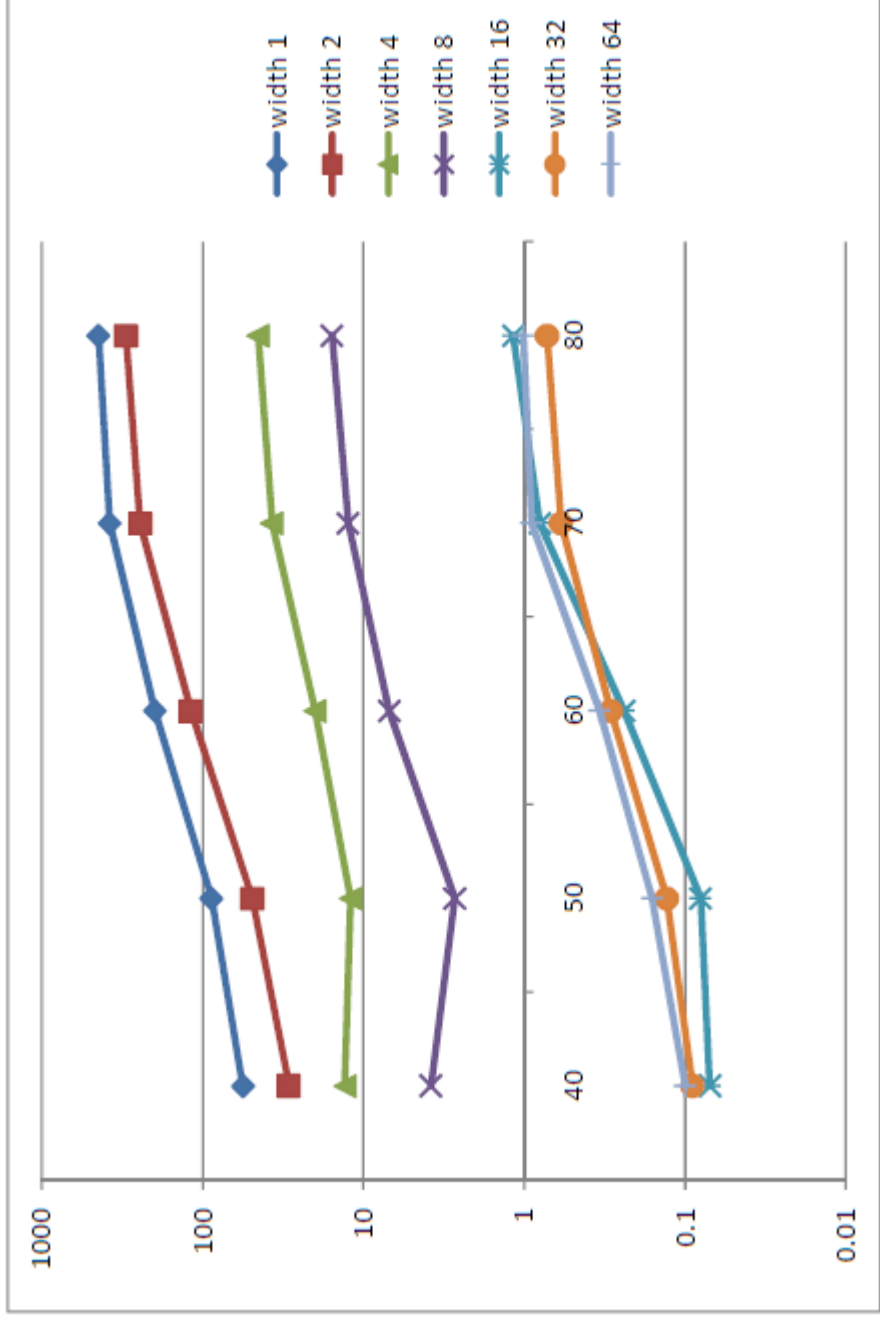
Multiple Amongs: Running Time



Domain store vs width **16 MDD**

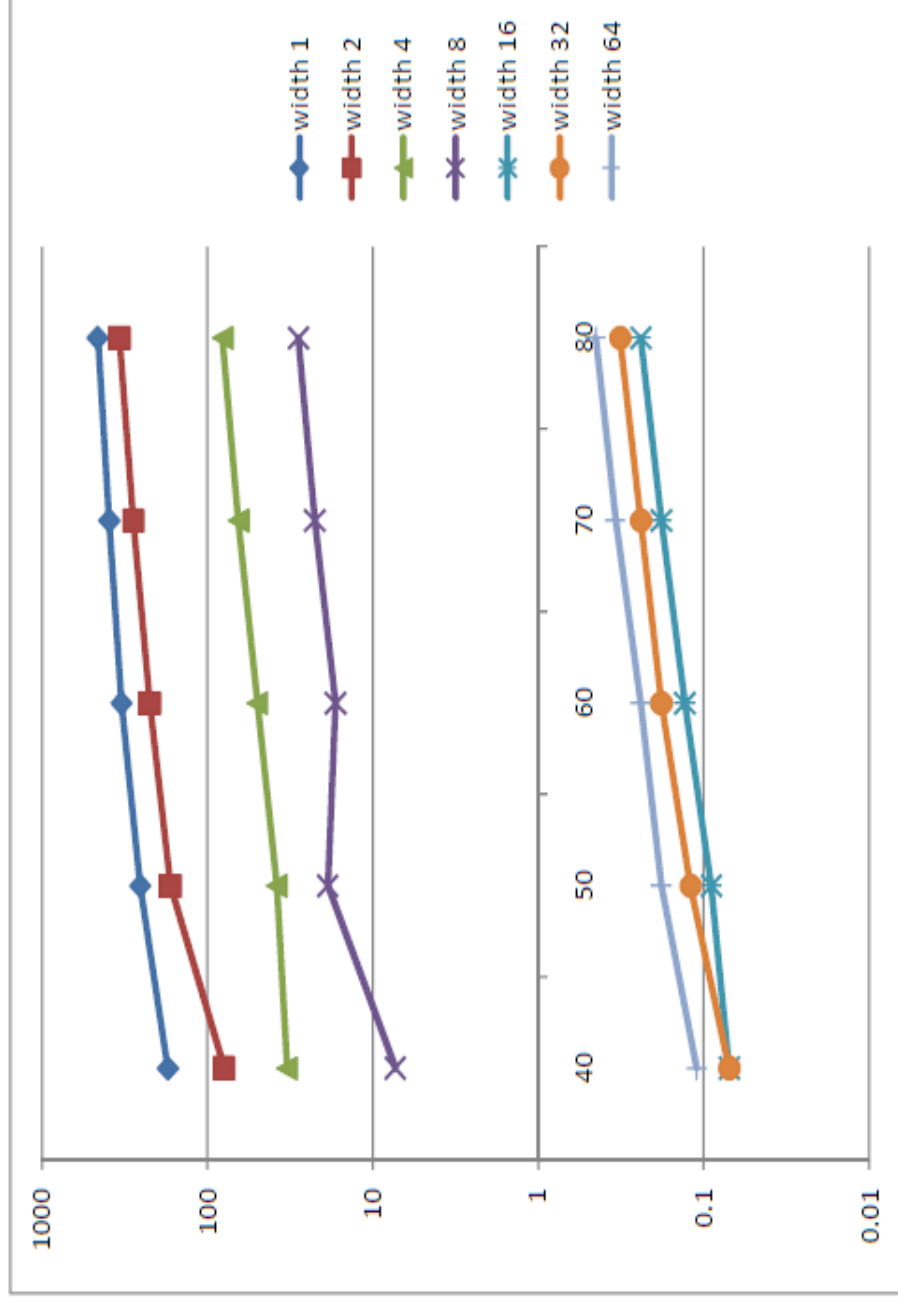
- Nurse rostering instances
 - Based on van Hoeve et al., *Constraints* 2009
 - Work 4-5 days per week
 - Max A days every B days (Max A/B)
 - Min C days every D days (Min A/B)
 - Time horizon ranges from 40 to 80 days
- Three problem classes
 - I: max 6/8, min 22/30
 - II: max 6/9, min 20/30
 - III: max 7/9, min 22/30

Nurse rostering problems



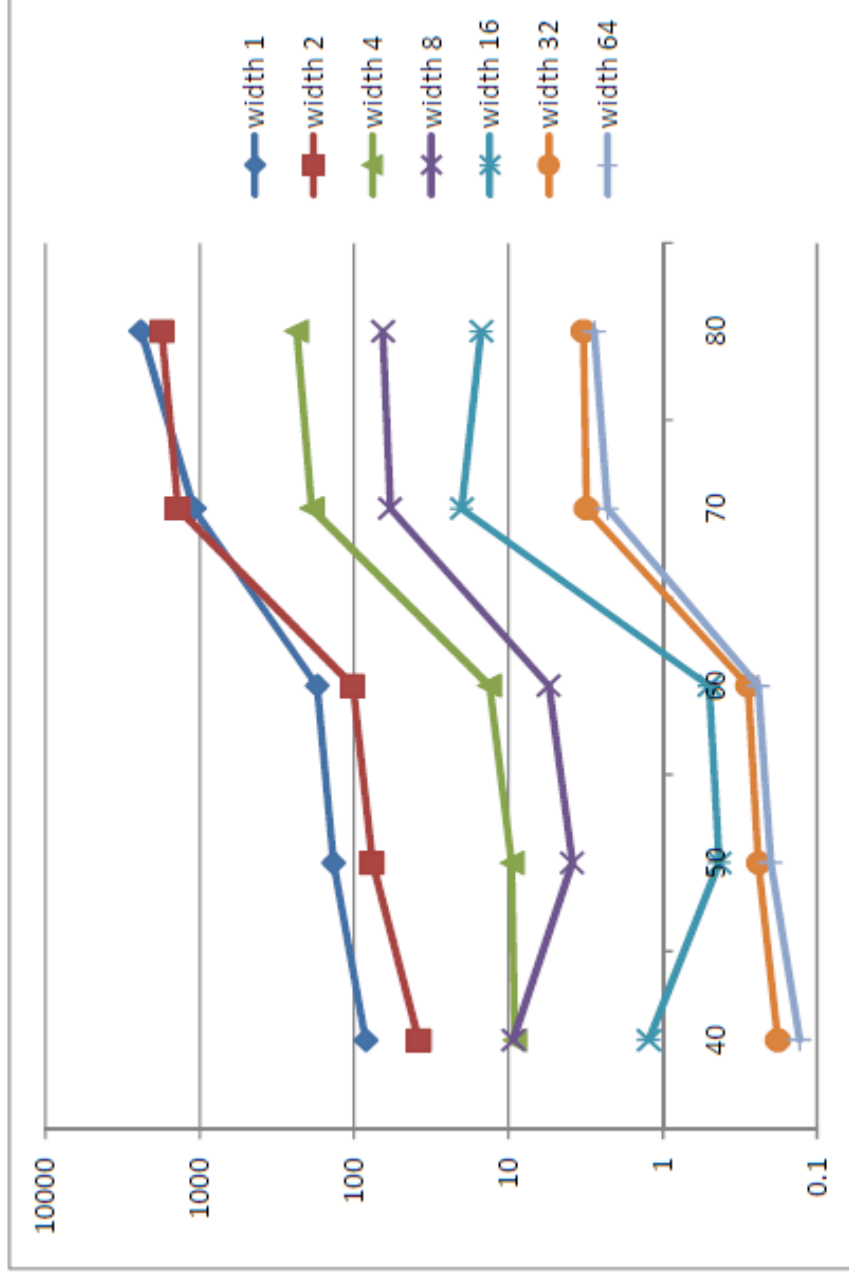
Computation time (sec) vs time horizon, Class I

Nurse rostering problems



Computation time (sec) vs time horizon, Class II

Nurse rostering problems



Computation time (sec) vs time horizon, Class III

- MDD-based propagation can be carried out according to a general scheme.
 - Equivalence testing for node splitting
 - Information operators for filtering
 - Yet the scheme allows exploitation of constraint-specific structure
- MDD-based constraint solving yields substantial speedup over domain store for multiple among constraints.
- Intensive processing at search nodes can pay off when more information is communicated between constraints.