Scheduling Home Hospice Care with Logic-Based Benders Decomposition

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> Lehigh University October 2016

Outline

- Logic-based Benders tutorial
 - The algorithm
 - Inference duality
 - Machine scheduling
 - Other applications
 - Logical inference and SAT
- Home health care
 - The problem
 - Logic-based Benders model
 - Computational results
 - Alternate relaxations
 - LBBD References

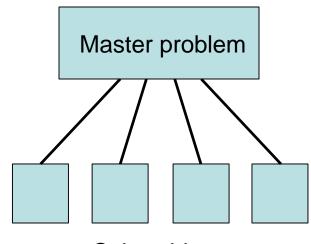
Decomposition

- **Decomposition** breaks a large problem into subproblems that can be solved separately.
 - But with some kind of communication among the subproblems.
 - Decomposition is an **essential strategy** for solving today's ever larger and more interconnected models.



Benders Decomposition

- Benders decomposition is a classical strategy that does not sacrifice overall optimality.
 - Separates the problem into a master problem and multiple subproblems.
 - Variables are partitioned between master and subproblems.
 - Exploits the fact that the problem may radically simplify when the master problem variables are fixed to a set of values.



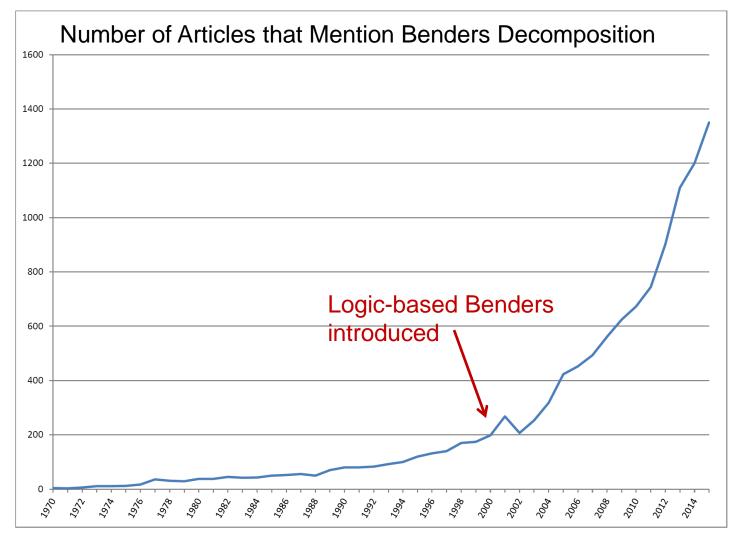
Benders Decomposition

- But classical Benders decomposition has
 a serious limitation.
 - The subproblems must be **linear programming** problems.
 - Or continuous nonlinear programming problems.
 - The linear programming dual provides the Benders cuts.

Benders 1962

- Logic-based Benders decomposition attempts to overcome this limitation.
 - The subproblems can, in principle, be any kind of optimization problem.
 - The Benders cuts are obtained from an inference dual.
 - Speedup over state of the art can be several orders of magnitude.
 - Yet the Benders cuts must be designed specifically for every class of problems.

JH 1996, 2000 JH & Ottosson 2003



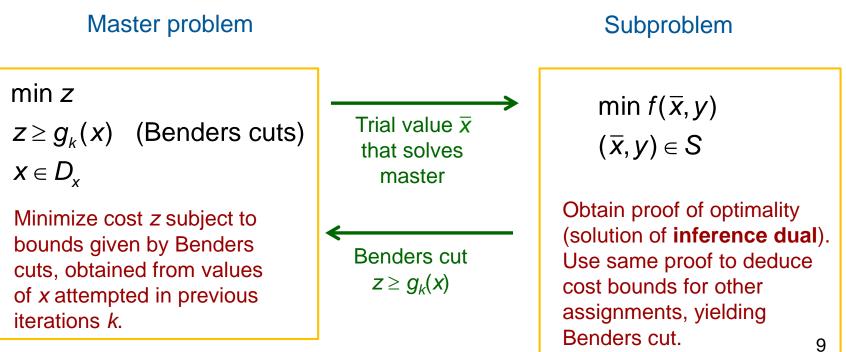
Source: Google Scholar

 Logic-based Benders decomposition solves a problem of the form

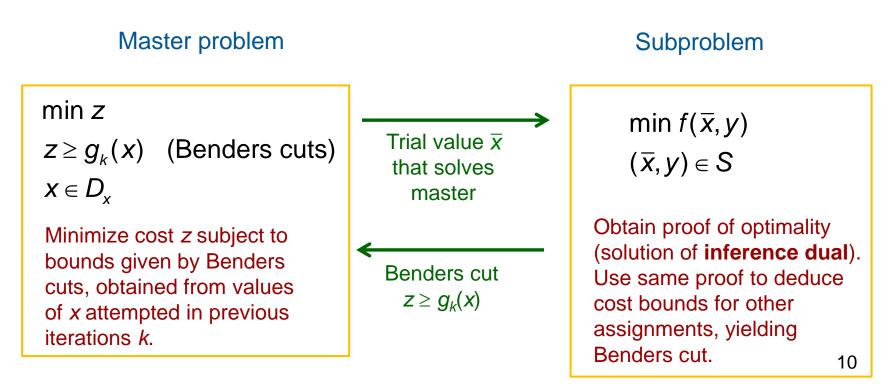
 $\min f(x, y)$ $(x, y) \in S$ $x \in D_x, y \in D_y$

Where the problem simplifies when *x* is fixed to a specific value.

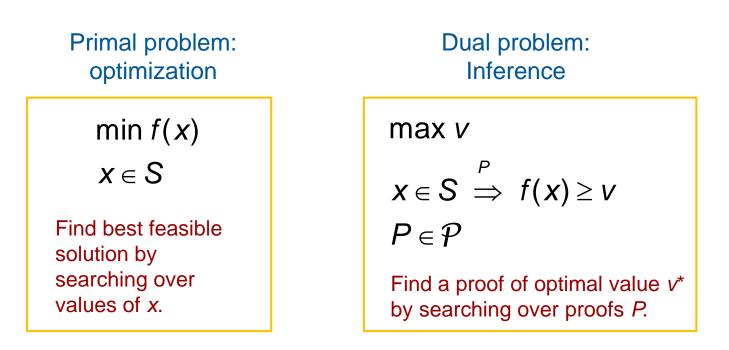
- Decompose problem into master and subproblem. ٠
 - Subproblem is obtained by fixing x to solution value in master problem.



- Iterate until master problem value equals best subproblem value so far.
 - This yields optimal solution.

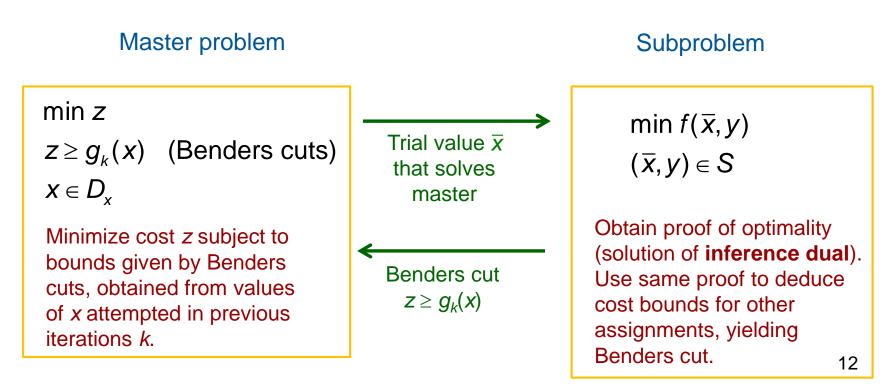


• Fundamental concept: inference duality



In classical LP, the proof is a tuple of dual multipliers

- The proof that solves the dual in iteration k gives a bound $g_k(\bar{x})$ on the optimal value.
 - The same proof gives a bound $g_k(x)$ for other values of x.



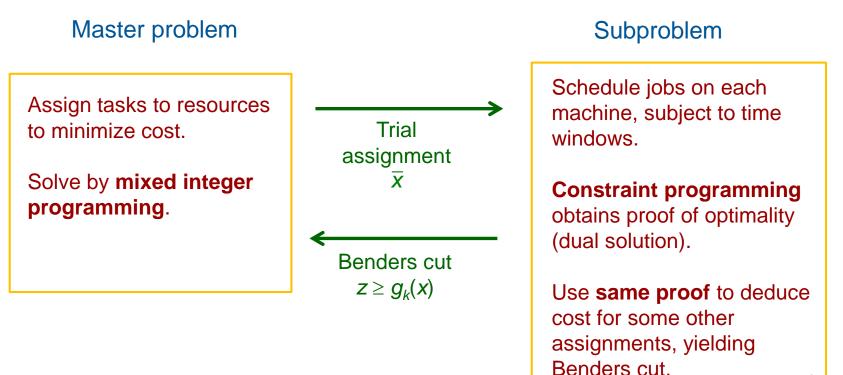
- Popular optimization duals are special cases of the inference dual.
 - Result from different choices of inference method.
 - For example....
 - Linear programming dual (gives classical Benders cuts)
 - Lagrangean dual
 - Surrogate dual
 - Subadditive dual

- Assign tasks to machines.
- Then schedule tasks assigned to each machine.
 - Subject to time windows.
 - Cumulative scheduling: several tasks can run simultaneously, subject to resource limits.
 - Scheduling problem decouples into a separate problem for each machine.



Jain & Grossmann 2001

- Assign tasks in master, schedule in subproblem.
 - Combine mixed integer programming and constraint programming



- Objective function
 - Cost is based on task assignment only.

cost = $\sum_{ij} c_{ij} x_{ij}$, $x_{ij} = 1$ if task *j* assigned to resource *i*

- So cost appears only in the **master problem**.
- Scheduling subproblem is a feasibility problem.

- Objective function
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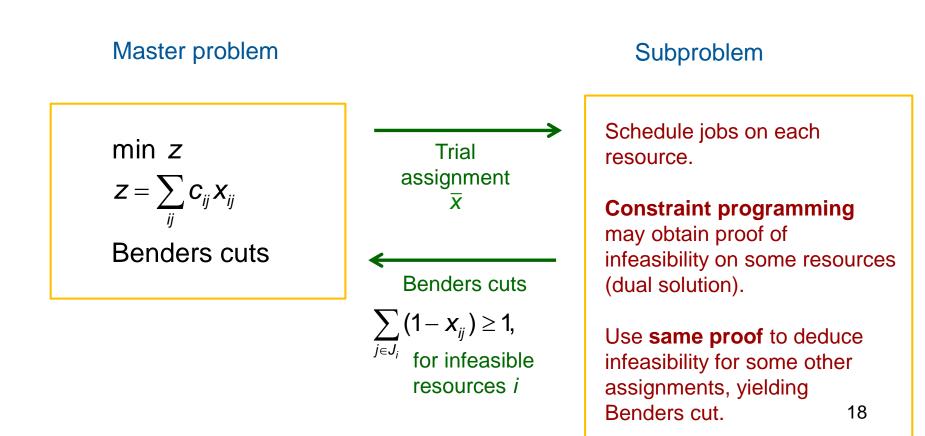
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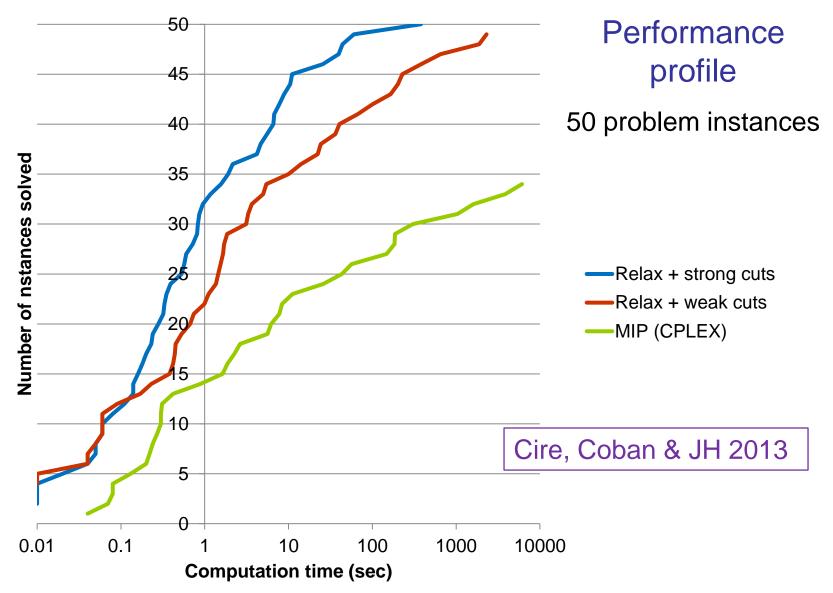
- So cost appears only in the **master problem**.
- Scheduling subproblem is a feasibility problem.
- Benders cuts

- They have the form
$$\sum_{j \in J_i} (1 - x_{ij}) \ge 1$$
, all *i*

- where J_i is a set of tasks that create infeasibility when assigned to resource *i*.

• Resulting Benders decomposition:





- Planning and scheduling:
 - Machine allocation and scheduling
 - Steel production scheduling
 - Chemical batch processing (BASF, etc.)
 - Auto assembly line management (Peugeot-Citroën)
 - Allocation and scheduling of multicore processors (IBM, Toshiba, Sony)
 - Worker assignment in a queuing
 - environment



- Other scheduling
 - Lock scheduling
 - Shift scheduling
 - Permutation flow shop scheduling with time lags
 - Resource-constrained scheduling
 - Hospital scheduling
 - Optimal control of dynamical systems
 - Sports scheduling



- Routing and scheduling
 - Vehicle routing
 - Home health care
 - Food distribution
 - Automated guided vehicles in flexible manufacturing
 - Traffic diversion around blocked routes
 - Concrete delivery



- Location and Design
 - Wireless local area network design
 - Facility location-allocation
 - Stochastic facility location and fleet management
 - Capacity and distanceconstrained plant location
 - Queuing design and control





- Other
 - Logical inference
 - Logic circuit verification
 - Bicycle sharing
 - Service restoration in a network
 - Inventory management
 - Supply chain management
 - Space packing



- A fundamental problem in the information age.
 - Can use SAT solvers or logic-based Benders to deduce facts from a knowledge base.
 - SAT solvers are a **special case** of Benders!



- Draw inferences from a clause set
 - Infer everything we can about propositions x_1 , x_2 , x_3

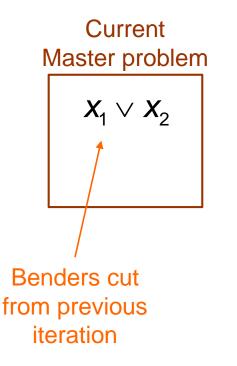
We can deduce $X_1 \lor X_2$

$$X_1 \vee X_3$$

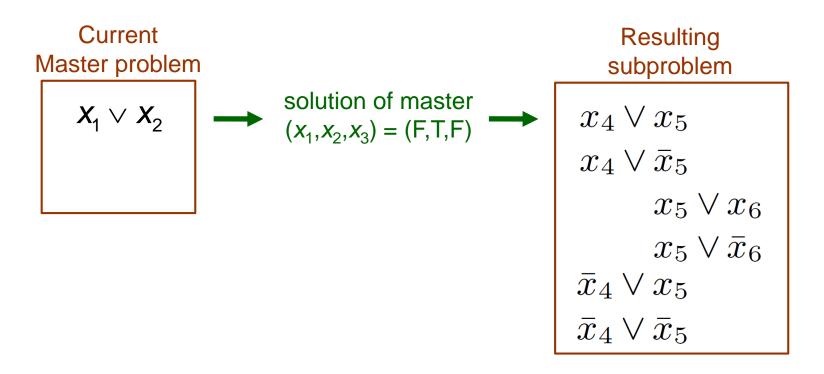
This is a **projection** onto x_1 , x_2 , x_3

JH 2015

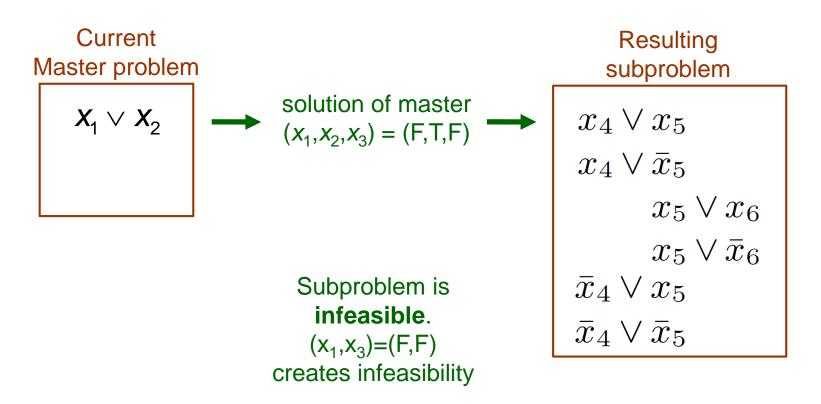
- Benders decomposition computes the projection.
 - Benders cuts describe projection onto master problem variables.



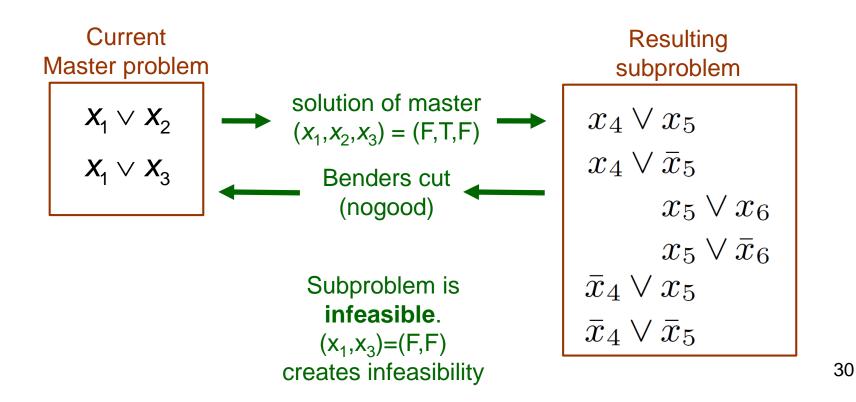
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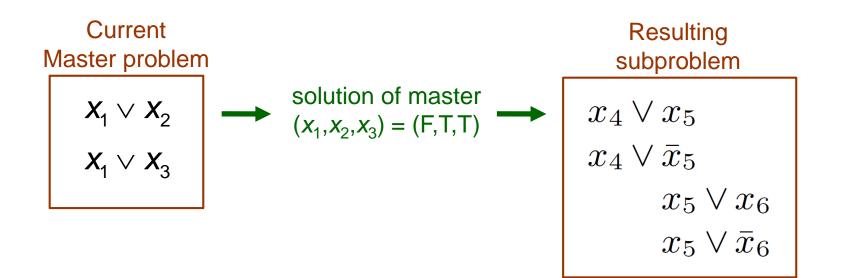
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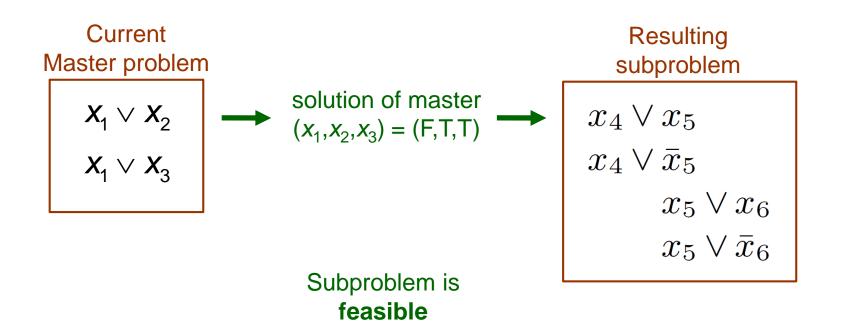
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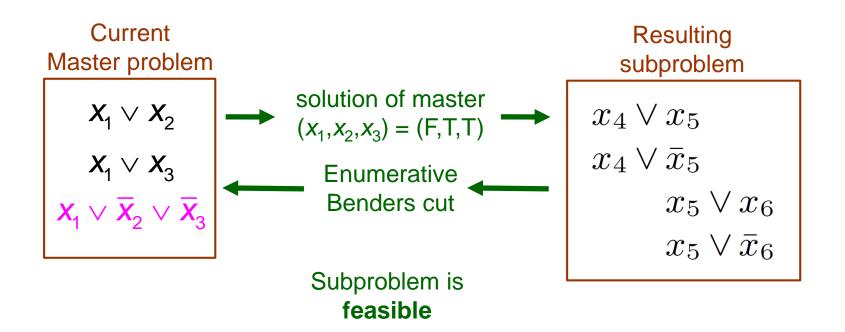
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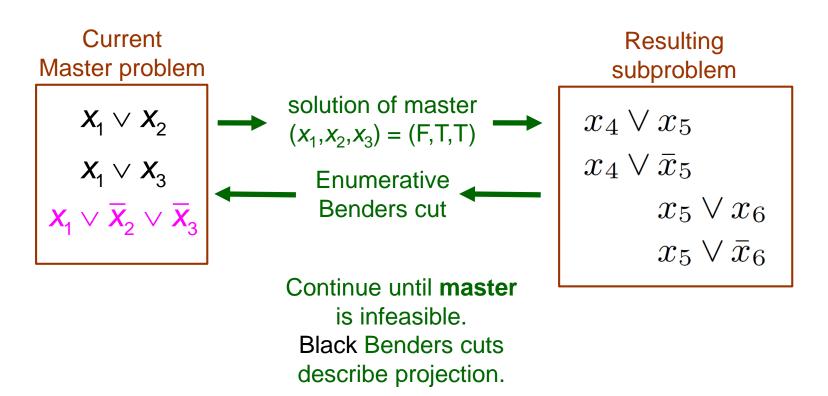
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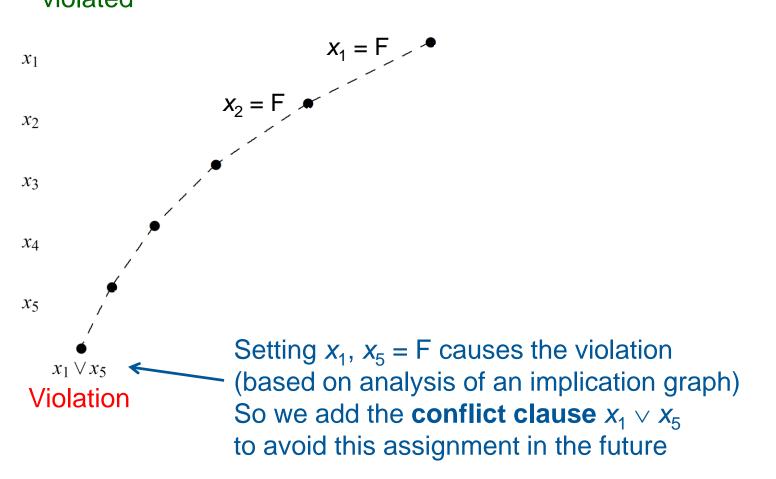


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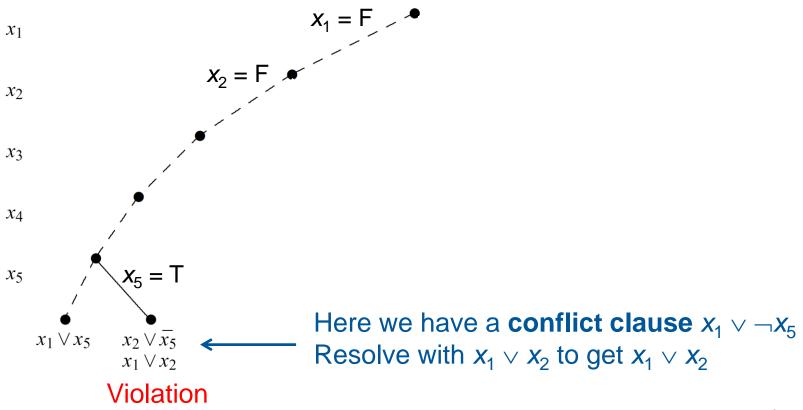


- Satisfiability methods solve the problem by generating Benders cuts!
 - Conflict clauses = Benders cuts

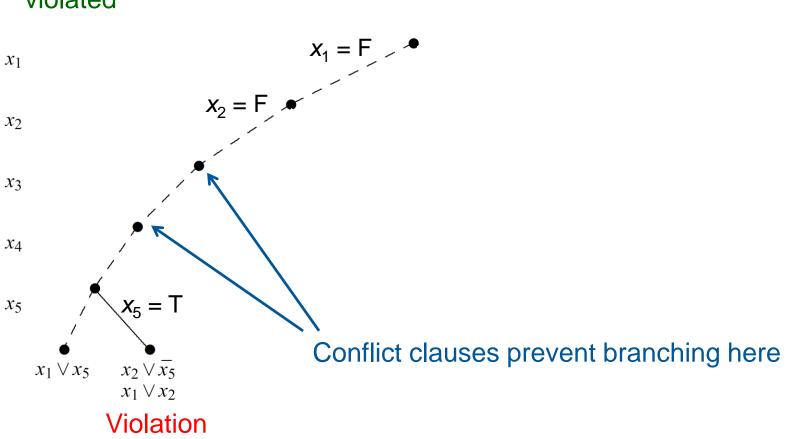
Start branching on variables in depth-first fashion. At each node of the branching tree, check if a clause is violated



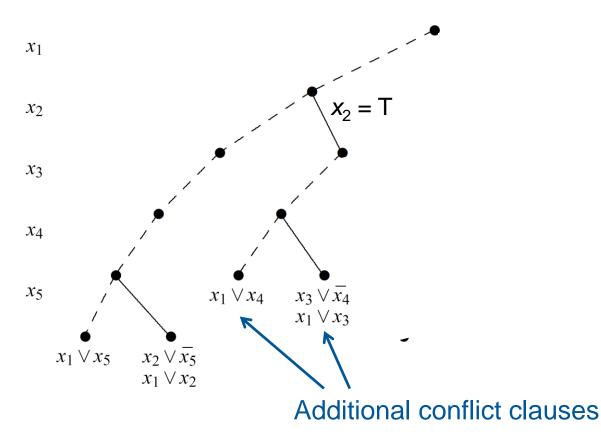
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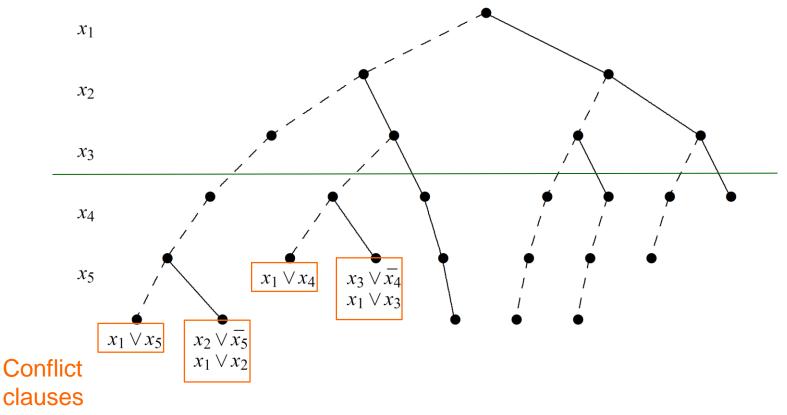
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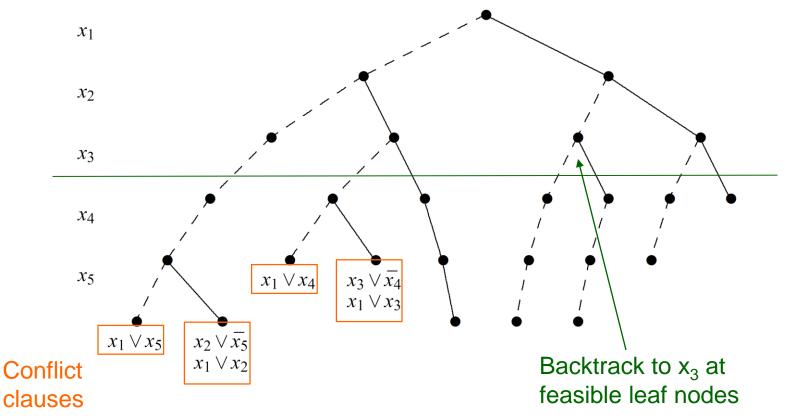
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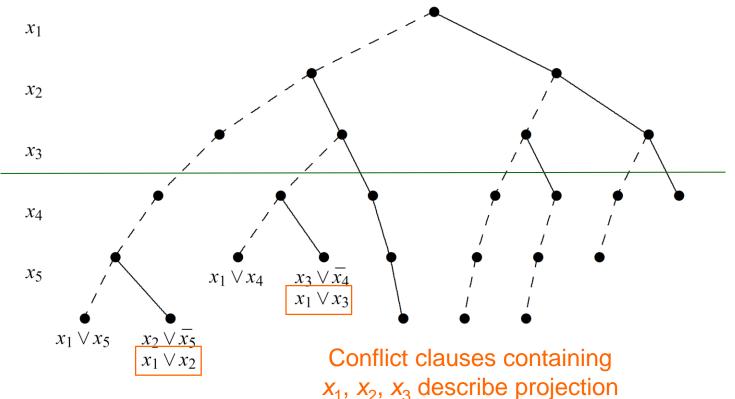
- Benders cuts = conflict clauses in a SAT algorithm
 - Branch on x_1 , x_2 , x_3 first.



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- General home health care problem.
 - Assign aides to homebound patients.
 - ...subject to constraints on aide qualifications and patent preferences.
 - One patient may require a team of aides.
 - Route each aide through assigned patients, observing time windows.
 - ...subject to constraints on hours, breaks, etc.



- A large industry, and rapidly growing.
 - Roughly as large as all courier and delivery services.

Projected Growth of Home Health Care Industry

	2014	2018
U.S. revenues, \$ billions	75	150
World revenues, \$ billions	196	306

Increase in U.S. Employment, 2010-2020

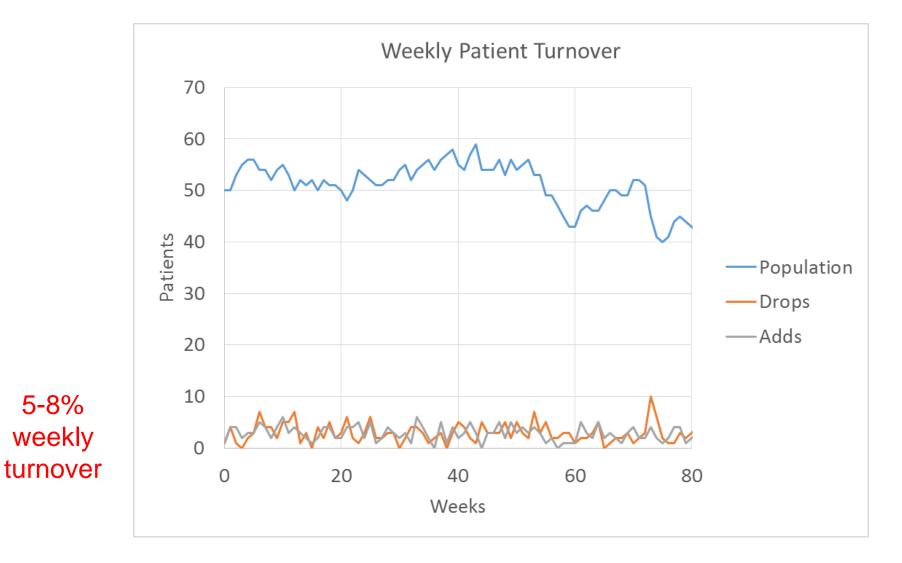
Home health care industry	70%
Entire economy	14%

- Advantages of home health care
 - Lower cost
 - Hospital & nursing home care is very expensive.
 - No hospital-acquired infections
 - Less exposure to superbugs.
 - Preferred by patients
 - Comfortable, familiar surroundings of home.
 - Sense of control over one's life.
 - Supported by new equipment & technology
 - IT integration with hospital systems.
 - Online consulting with specialists.

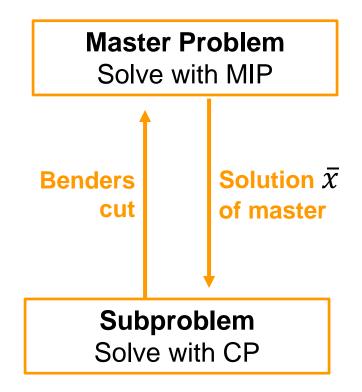
- Critical factor to realize cost savings:
 - Aides must be **efficiently** scheduled.
- This is our task.
 - Focus on home hospice care.



- Distinguishing characteristics of hospice care
 - Personal & household services
 - Regular weekly schedule
 - For example, Mon-Wed-Fri at 9 am.
 - Same aide each visit
 - Long planning horizon
 - Several weeks
 - Rolling schedule
 - Update schedule as patient population evolves.

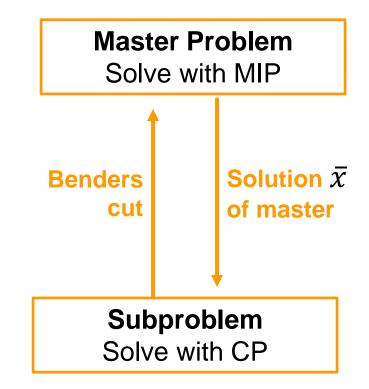


- Solve with Benders decomposition.
 - Assign aides to patients in master problem.
 - Maximize number of patients served by a given set of aides.

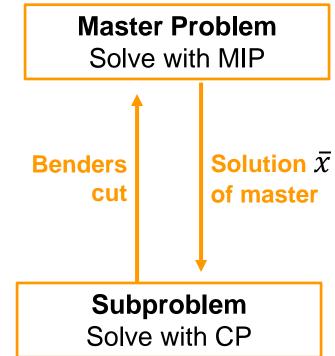


Heching & JH 2016

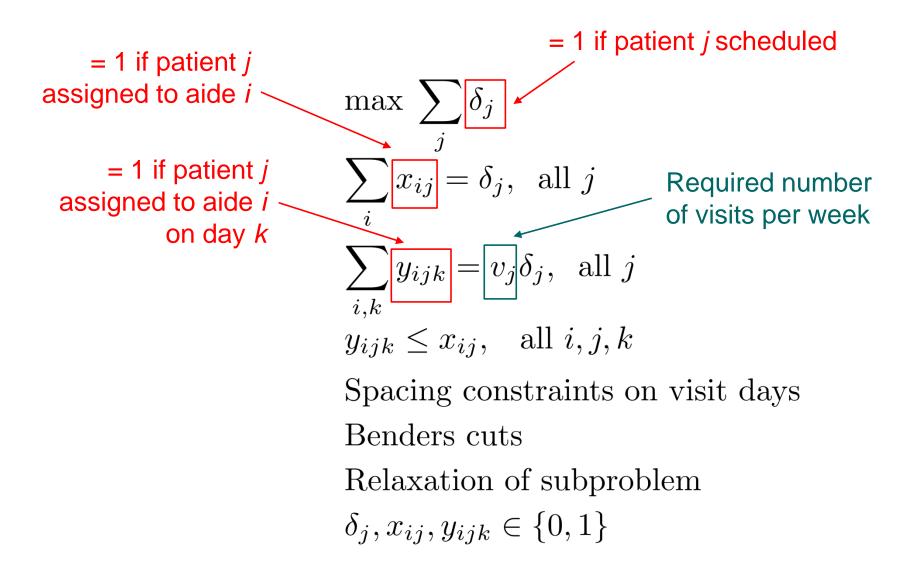
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- Solve with Benders decomposition.
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 - Maximize number of patients served by a given set of aides.
 - Schedule home visits in subproblem.
 - Cyclic weekly schedule.
 - No visits on weekends.
 - Subproblem decouples into a scheduling problem for each aide and each day of the week.



Master Problem



Master Problem

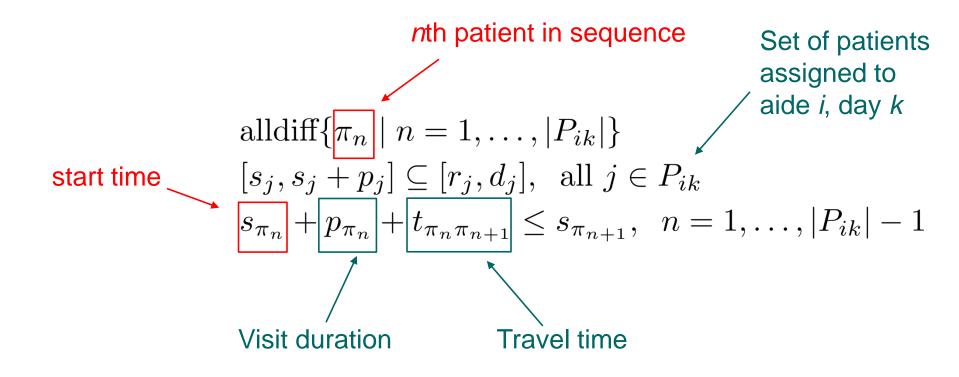
- For a rolling schedule:
 - Schedule new patients, drop departing patients from schedule.
 - Provide continuity for remaining patients as follows:
 - Old patients served by same aide on same days.
 - Fix $y_{ijk} = 1$ for the relevant aides, patients, and days.

Master Problem

- For a rolling schedule:
 - Schedule new patients, drop departing patients from schedule.
 - Provide continuity for remaining patients as follows:
 - Old patients served by same aide on same days.
 - Fix $y_{ijk} = 1$ for the relevant aides, patients, and days.
 - Alternative: Also served at same time.
 - Fix time windows to enforce their current schedule.
 - Alternative: served only by same aide.
 - Fix $x_{ij} = 1$ for the relevant aides, patients.

Subproblem

Scheduling problem for aide *i*, day *k*



Modeled with interval variables in CP solver.

- Generate a cut for each infeasible scheduling problem.
 - Solution of subproblem inference dual is a **proof** of infeasibility.
 - The proof may show **other** patient assignments to be infeasible.
 - Generate **nogood cut** that rules out these assignments.

- Generate a cut for each infeasible scheduling problem.
 - Solution of subproblem inference dual is a **proof** of infeasibility.
 - The proof may show **other** patient assignments to be infeasible.
 - Generate nogood cut that rules out these assignments.
 - Unfortunately, we **don't have access** to infeasibility proof in CP solver.

- So, strengthen the nogood cuts heuristically.
 - Find a smaller set of patients that create infeasibility...
 - ...by re-solving the each infeasible scheduling problem repeatedly.

$$\sum_{j \in \bar{P}_{ik}} (1 - y_{ijk}) \ge 1$$

Reduced set of patients whose assignment to aide *i* on day *k* creates infeasibility

- Auxiliary cuts based on symmetries.
 - A cut for valid for aide *i*, day *k* is also valid for aide *i* on other days.
 - This gives rise to a large number of cuts.
 - The auxiliary cuts can be summed without sacrificing optimality.
 - Original cut ensures convergence to optimum.
 - This yields 2 cuts per aide:

$$\sum_{j\in\bar{P}_{ik}} (1-y_{ijk}) \ge 1$$

$$\sum_{k \neq k} \sum_{j \in \bar{P}_{ik}} (1 - y_{ijk'}) \ge 4$$

- Include relaxation of subproblem in the master problem.
 - Necessary for good performance.
 - Use time window relaxation for each scheduling problem.
 - Simplest relaxation for aide *i* and day *k*:

$$\sum_{j \in J(a,b)} p_j y_{ijk} \le b - a$$

$$f$$
Set of patients whose time window

fits in interval [*a*, *b*].

Can use several intervals.

- This relaxation is very weak.
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 - Basic idea: Augment visit duration p_j with travel time to (or from) location j from closest patient or aide home base.
 - This is weak unless most assignments are fixed.
 - As in rolling schedule.
 - We partition day into 2 intervals.
 - Morning and afternoon.
 - Simplifies handling of aide time windows and home bases.
 - All patient time windows are in morning or afternoon.

Time window relaxation for aide *i*, day *k* using intervals [*a*,*b*], [*b*,*c*]

$$\sum_{\substack{j \in J(a,b)}} p'_{ijk} y_{ijk} \le b - a$$
$$\sum_{\substack{j \in J(b,c)}} p''_{ijk} y_{ijk} \le c - b$$

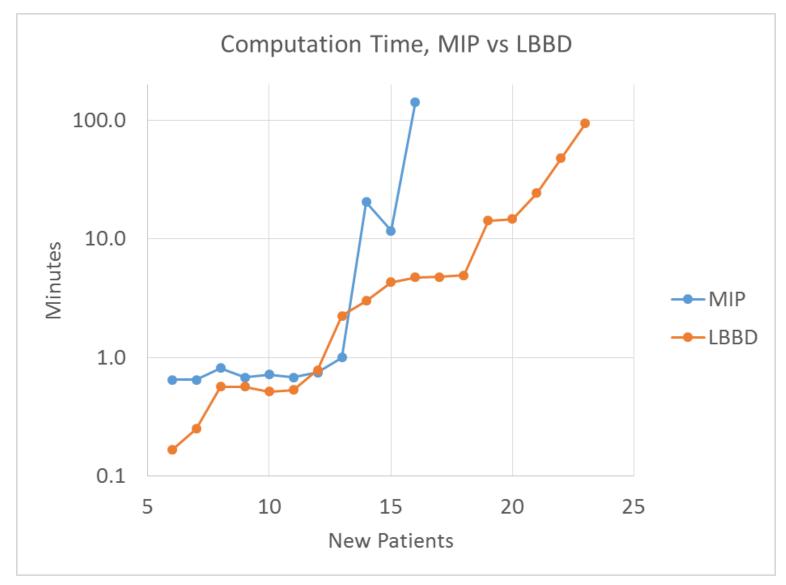
where

$$[a, c] = \text{time window for aide } i$$
$$p'_{ijk} = p_j + \min \{ t_{ij}, \min_{j' \in Q_{ik}} \{ t_{j'j} \} \}$$
$$p''_{ijk} = p_j + \min \{ \min_{j' \in Q_{ik}} \{ t_{jj'} \}, c \}$$

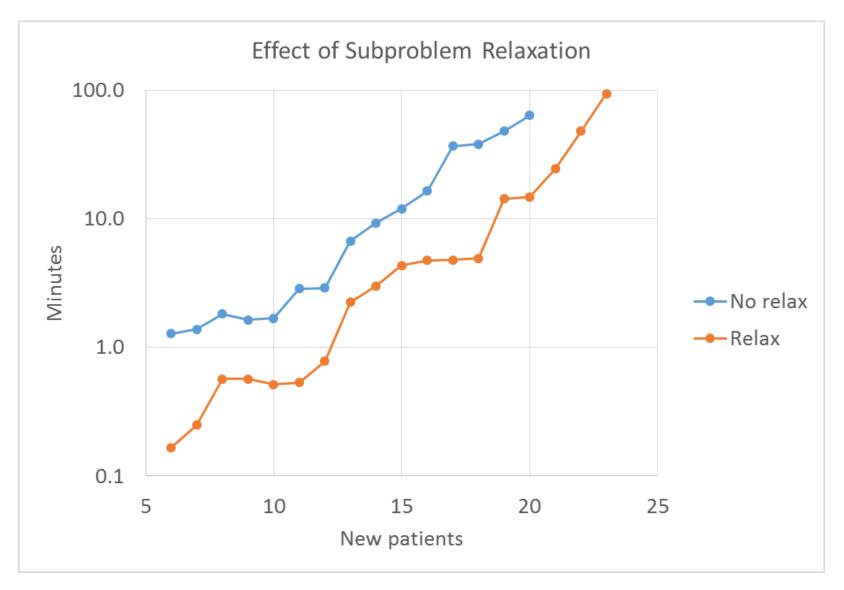
and where $Q_{ik} = \{$ patients unassigned or assigned to aide *i*, day *k* $\}$

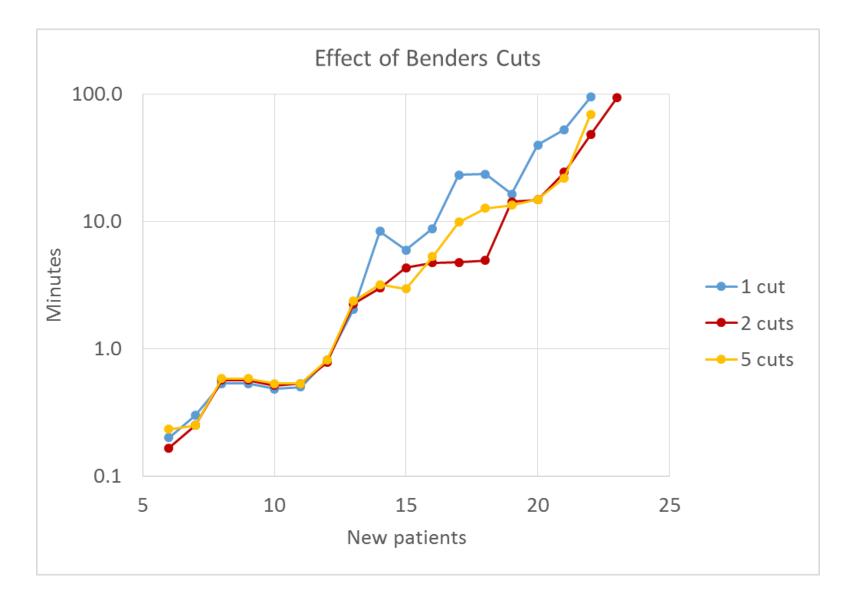
- Dataset
 - 60 home hospice patients
 - 2, 3 or 5 visits per week (not on weekends)
 - 18 health care aides with time windows
 - Actual travel distances
- Solver
 - **LBBD:** IBM OPL Optimization Studio 12.6.2
 - CPLEX + CP Optimizer + user-supplied script
 - MIP: CPLEX in OPL Studio
 - Modified multicommodity flow model of VRPTW
- Computer
 - Laptop with Intel Core i7
 - 7.75 GB RAM

- Instance generation
 - Start with (suboptimal) solution for the 60 patients
 - Fix this schedule for first *n* patients.
 - Schedule remaining 60 *n* patients
 - Use 8 of the 18 aides to cover new patients
 - As well as the old patients they already cover.
 - This puts us near the phase transition.



- Practical implications
 - MIP or LBBD will work for smaller instances
 - LBBD scales up to realistic size
 - One month advance planning in 60 patient population
 - Assuming 5-8% weekly turnover
 - Advantage of **exact** solution method
 - We know **for sure** whether existing staff will cover projected demand.





- Other relaxations
 - Multicommodity flow relaxation
 - Master problem too large, solves slowly
 - n^2 flow variables, where n = number of patients
 - Master must be re-solved in each iteration
 - Relaxation useless until many variables are fixed in B&B

Computational Tests

• Other relaxations

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 - Master problem too large, solves slowly
 - n^2 flow variables, where n = number of patients
 - Master must be re-solved in each iteration
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- Assignment relaxation
 - Master problem still too large, solves slowly.
 - Relaxation very weak without separating TSP cuts.

Branch & Check

- Idea: use stronger relaxation with branch & check
 - Branch & check solves master problem **once** with search tree.
 - At feasible nodes, solve subproblem to obtain Benders cut.
 - Not the same as branch & bound.
- Large multicommodity or assignment relaxation is only solved once.

JH 2000 Thorsteinsson 2003

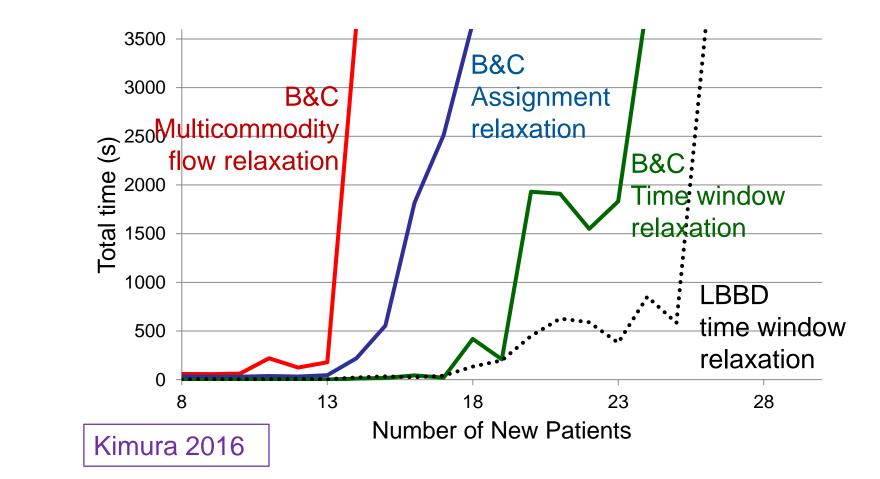
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 - At feasible nodes, solve subproblem to obtain Benders cut.
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- Large multicommodity or assignment relaxation is only solved once.
- However, performance is **worse**...

JH 2000 Thorsteinsson 2003

Branch & Check

Total Solve Time vs Relaxation



Branch & check

- What is going on?
 - Because of superior relaxation, fewer feasible leaf nodes.
 - So fewer Benders cuts.
 - Less information obtained from subproblem.er



Branch & check

- What is going on?
 - Because of superior relaxation, fewer feasible leaf nodes.
 - So fewer Benders cuts.
 - Less information obtained from subproblem.er
- Good news...
 - This reimplementation of LBBD is substantially faster than OPL implementation.
 - Uses C++, SCIP, and Gecode.



Conclusions

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 - ...when computing a **rolling** schedule
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 - Relaxation that grows quadratically is too large
 - Such as multicommodity flow and assignment relaxations
 - Relaxation must grow only linearly
 - Such as time window relaxation

Conclusions

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 - Such as multicommodity flow and assignment relaxations
 - Relaxation must grow only linearly
 - Such as time window relaxation
- LBBD superior to branch & check

References

Applications of Logic-Based Benders Decomposition

Benders decomposition [7] was introduced in 1962 to solve applications that become linear programming (LP) problems when certain *search variables* are fixed. "Generalized" Benders decomposition, proposed by Geoffrion in 1972 [25], extended the method to nonlinear programming subproblems.

Logic-based Benders decomposition (LBBD) allows the subproblem to be any optimization problem. LBBD was introduced in [32], formally developed in 2000 [33], and tested computationally in [39]. *Branch and check* is introduced in [33] and tested computationally in [69]. *Combinatorial Benders cuts* for mixed integer programming are proposed in [18].

One of the first applications [43] was a planning and scheduling problem. Updated experiments [17] show that LBBD is orders of magnitude faster than state-of-the-art MIP, with the advantage over CP even greater). Similar results have been obtained for various planning and scheduling problems [15, 21, 30, 34, 35, 37, 71].

Other successful applications of LBBD include steel production scheduling [29], inventory management [74], concrete delivery [44], shop scheduling [3, 13, 27, 28, 59], hospital scheduling [57], batch scheduling in chemical plants [49, 70], computer processor scheduling [8, 9, 12, 22, 31, 46, 47, 48, 58, 62], logic circuit verification [40], shift scheduling [5, 60], lock scheduling [73], facility location [23, 66], space packing [20, 50], vehicle routing [19, 51, 53, 56, 61, 75], bicycle sharing [45], network design [24, 52, 63, 65], home health care [16], service restoration [26], supply chain management [68], food distribution [64], queuing design and control [67], optimal control of dynamical systems [11], propositional satisfiability [1], quadratic programming [2, 41, 42], chordal completion [10], and sports scheduling [14, 54, 55, 72]. LBBD is compared with branch and check in [6]. It is implemented in the general-purpose solver SIMPL [76].

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